

# Automatic Seismic Source Model Retrieval By Exploiting The Sentinel-1 DInSAR Co-seismic Displacement Maps Available Through The EPOSAR Service

Bradford

Leeds

Fernando Monterroso<sup>1</sup>, Simone Atzori<sup>2</sup>, Andrea Antonioli<sup>2</sup>,  
Claudio De Luca<sup>1</sup>, Nikos Svigkas<sup>2</sup>, Michele Manunta<sup>1</sup>, Matteo  
Quintiliani<sup>2</sup>, Riccardo Lanari<sup>1</sup>, Francesco Casu<sup>1</sup>.

1. IREA-CNR, Naples, Italy  
2. INGV, Rome, Italy

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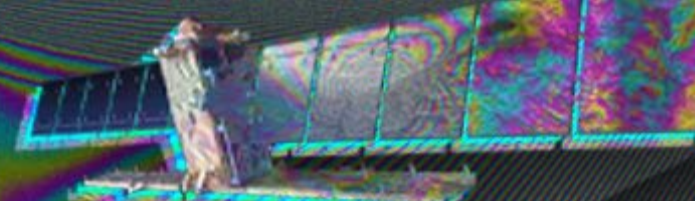
# Outline



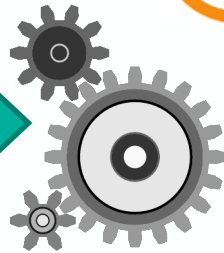
- EPOSAR service
- Automatic Processing chain implementation
  - Data setup
  - Non – linear Inversion
  - Linear inversion
- Experimental Results
- Conclusions and Future Developments



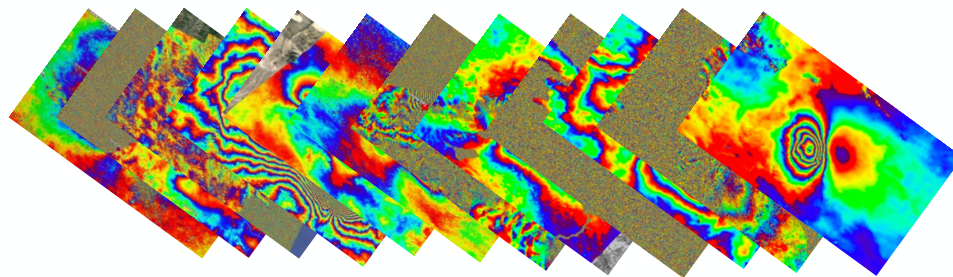
# EPOSAR Service



ISTITUTO NAZIONALE  
DI GEOFISICA E VULCANOLOGIA



Sentinel-1 Automatic  
DInSAR Processing



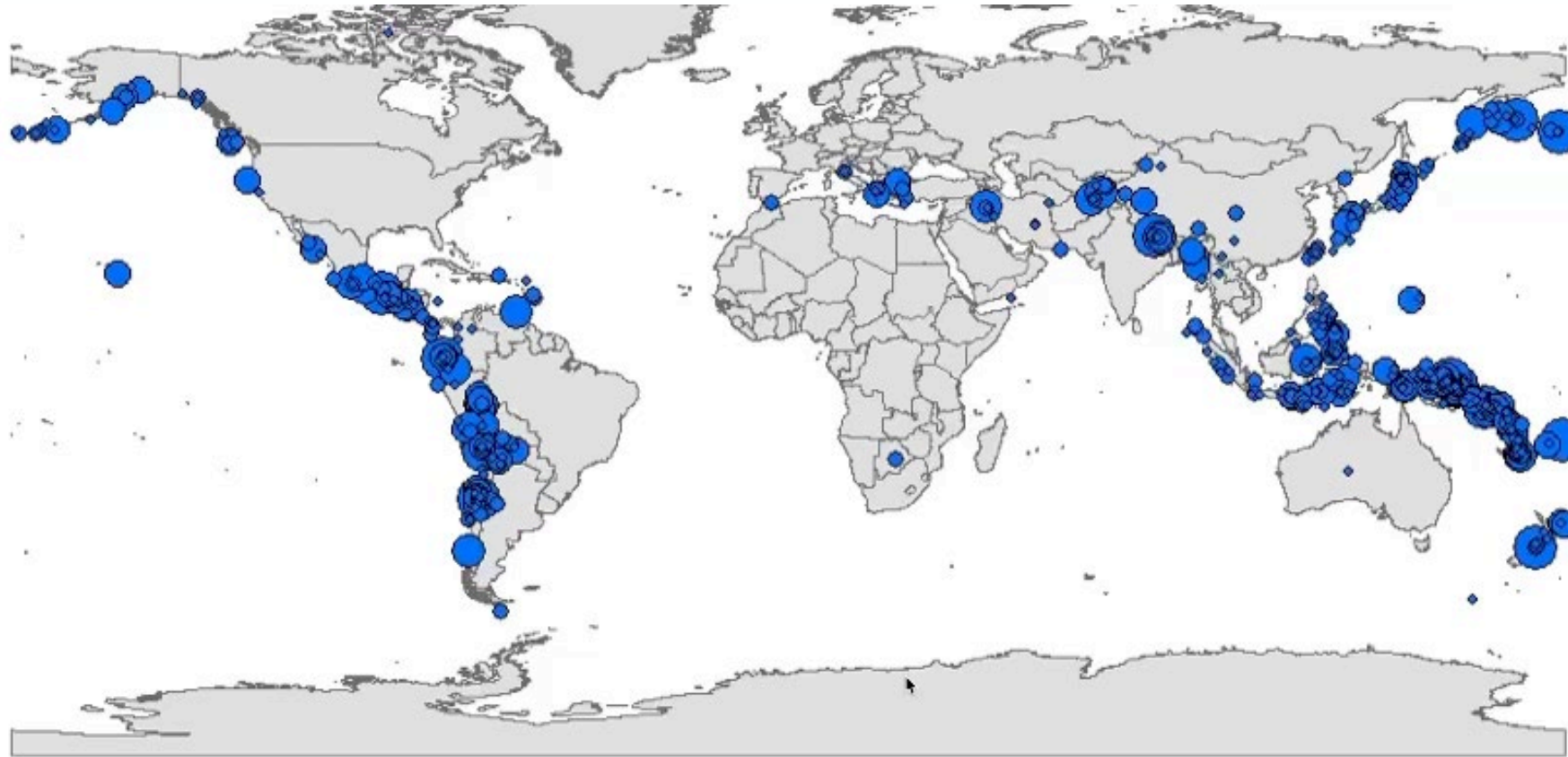
geohazards  
tep



<https://www.mdpi.com/843474>



# EPOSAR Service



608 Earthquakes  
(Sept 13, 2023)

45000 products

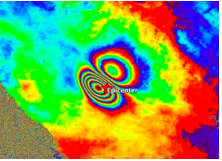
Interferograms,  
LOS Displacement maps  
Coherence maps



# Automatic Processing Chain Implementation



EPOSAR Service TCS  
Satellite Data



Data Setup

Area definition  
Pair selection  
Data Sampling

Non – Linear Inversion

inversion setup  
non-linear optimization  
convergence test  
setup update / end

Linear Inversion

source extension/subdivision  
damping definition  
 $d = Gm$  design  
 $G^{-1}$  calculation

Public Repository

source validation



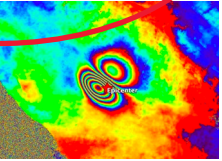
Focal Mechanism to Define  
area



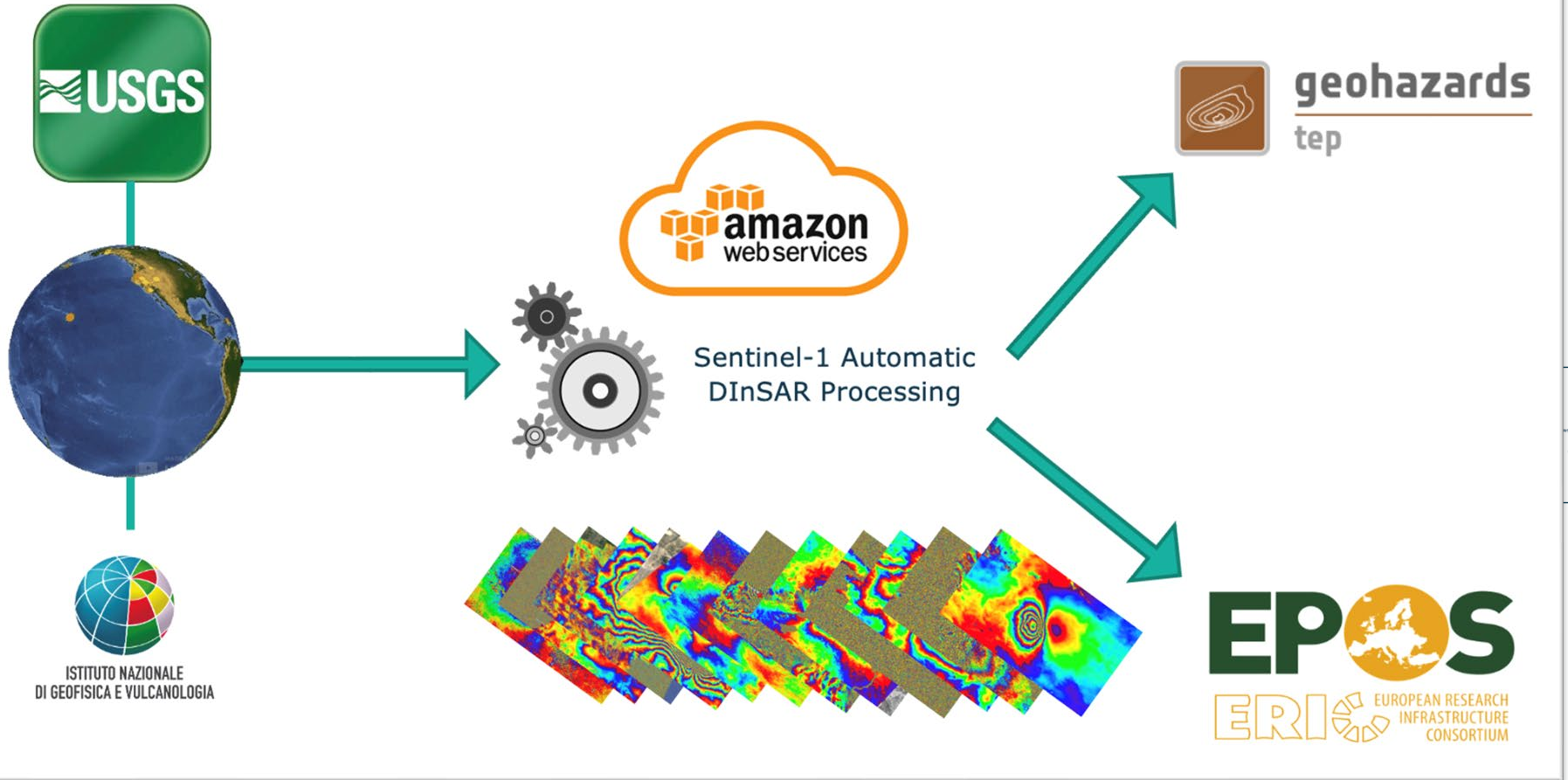
# Automatic Processing Chain Implementation



EPOSAR Service TCS  
Satellite Data



De  
Area of  
Pair se  
Data S



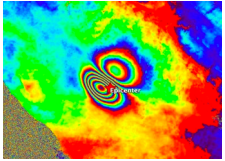
Focal Mechanism to Define  
area



# Automatic Processing Chain Implementation



EPOSAR Service TCS  
Satellite Data



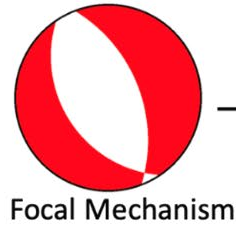
Data Setup

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Focal Mechanism to Define  
area

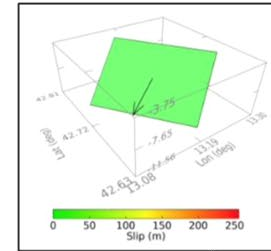


## Expected area affected by ground displacement

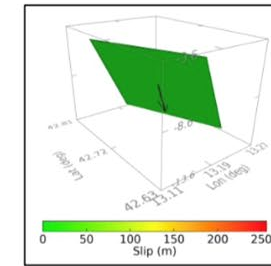


Focal Mechanism

Scaling factors  
(\*)

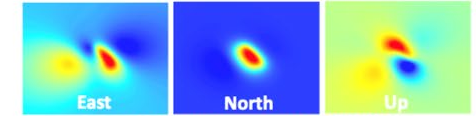


Fault plane 1

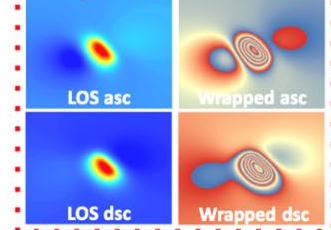


Fault plane 2

Forward mod.



if displacement > threshold



Forward mod.

*[idem]*

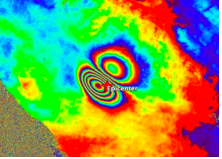
- *Rake-dependent scaling factors*
- *Slip refinement to match scalar moment*
- *Automatic definition of the output extent*

(\*) M. Leonard (2010) Earthquake Fault Scaling: Self-Consistent Relating of Rupture Length, Width, Average Displacement, and Moment Release, BSSA, doi: 10.1785/0120090189

itory



EPOSAR Service TCS  
Satellite Data



## Expected area affected by ground displacement

- **Criteria** **Bandar-e Genaveh, Iran earthquake 5.8 Mw (April 2021)**
  - the number of ascending and descending orbits used in the inversions must be the same;
  - shortest temporal baseline for each available track;
  - when the number of available ascending and descending tracks is different and a selection is necessary according to the first rule, priority is given to those better covering the affected area.
- **LOS unit vector files**
- **DEM**

Data Setup

Area definition  
Pair selection  
Data Sampling

Focal Mechanism to Define  
area

Monterroso et al (2022)

<https://doi.org/10.1016/j.jag.2023.103445>

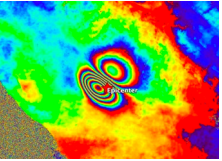




# Automatic Processing Chain Implementation



EPOSAR Service TCS  
Satellite Data



The Non-Linear optimization defines the fault location, geometry, and rupture mechanism with uniform slip

Data Setup

Area definition  
Pair selection  
Data Sampling

Non – Linear Inversion

inversion setup  
non-linear optimization  
convergence test  
setup update / end

Linear Inversion

Public Repository

source validation

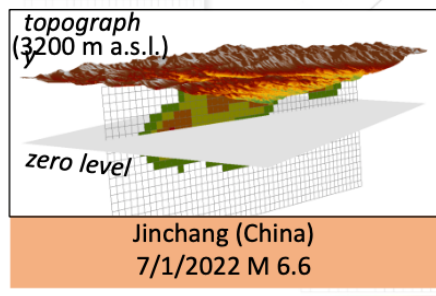
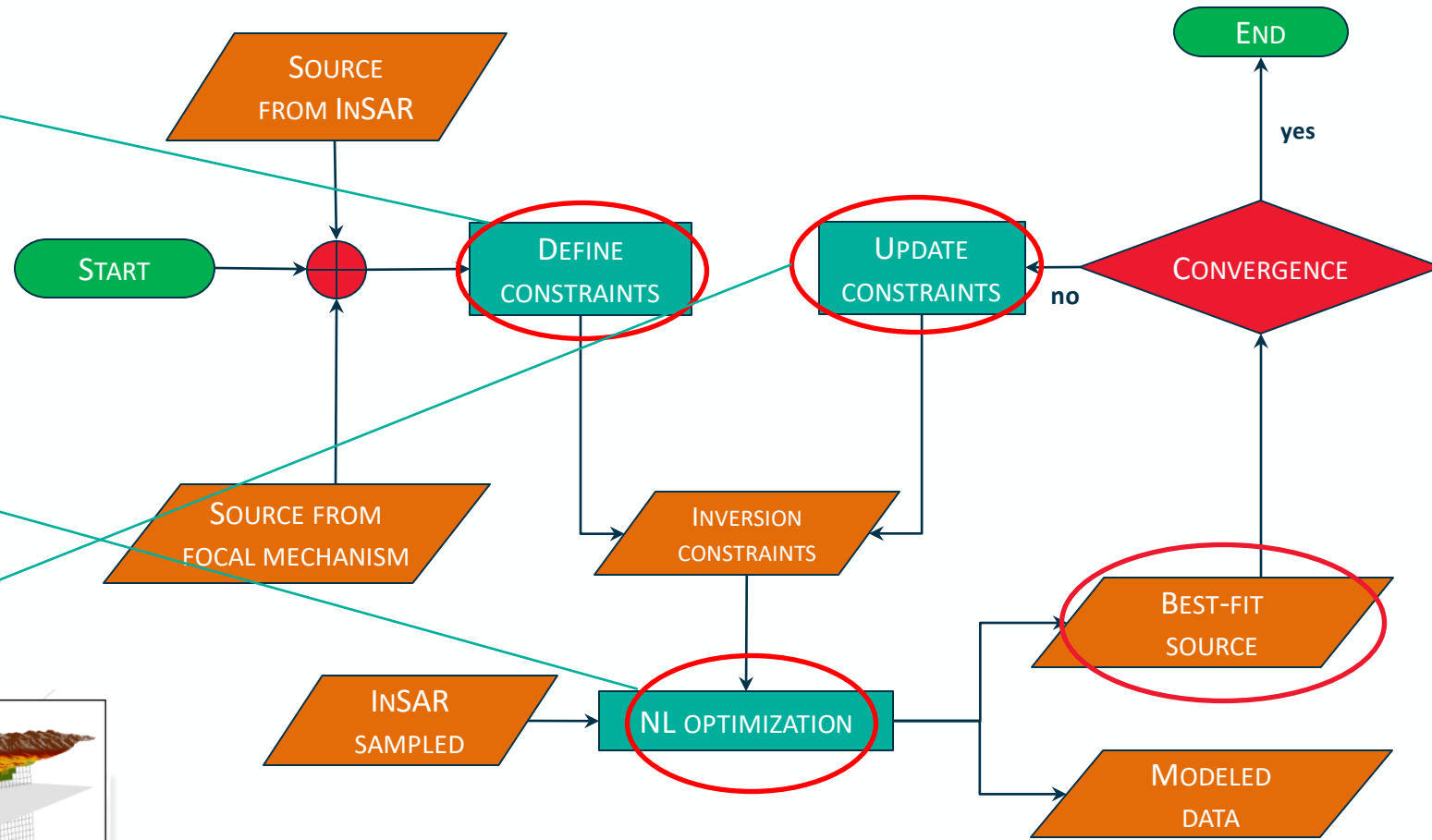


Focal Mechanism to Define  
area



# Automatic Non-Linear Inversion

- Define constrains
  - Range interval for every source parameter (Fault dimension, position, depth, orientation, rake and slip)
- Non linear optimization to find **the best - fit solution**, using the Levemberg – Marquardt scheme (Marquardt, 1963).
- Update Constrains algorithm



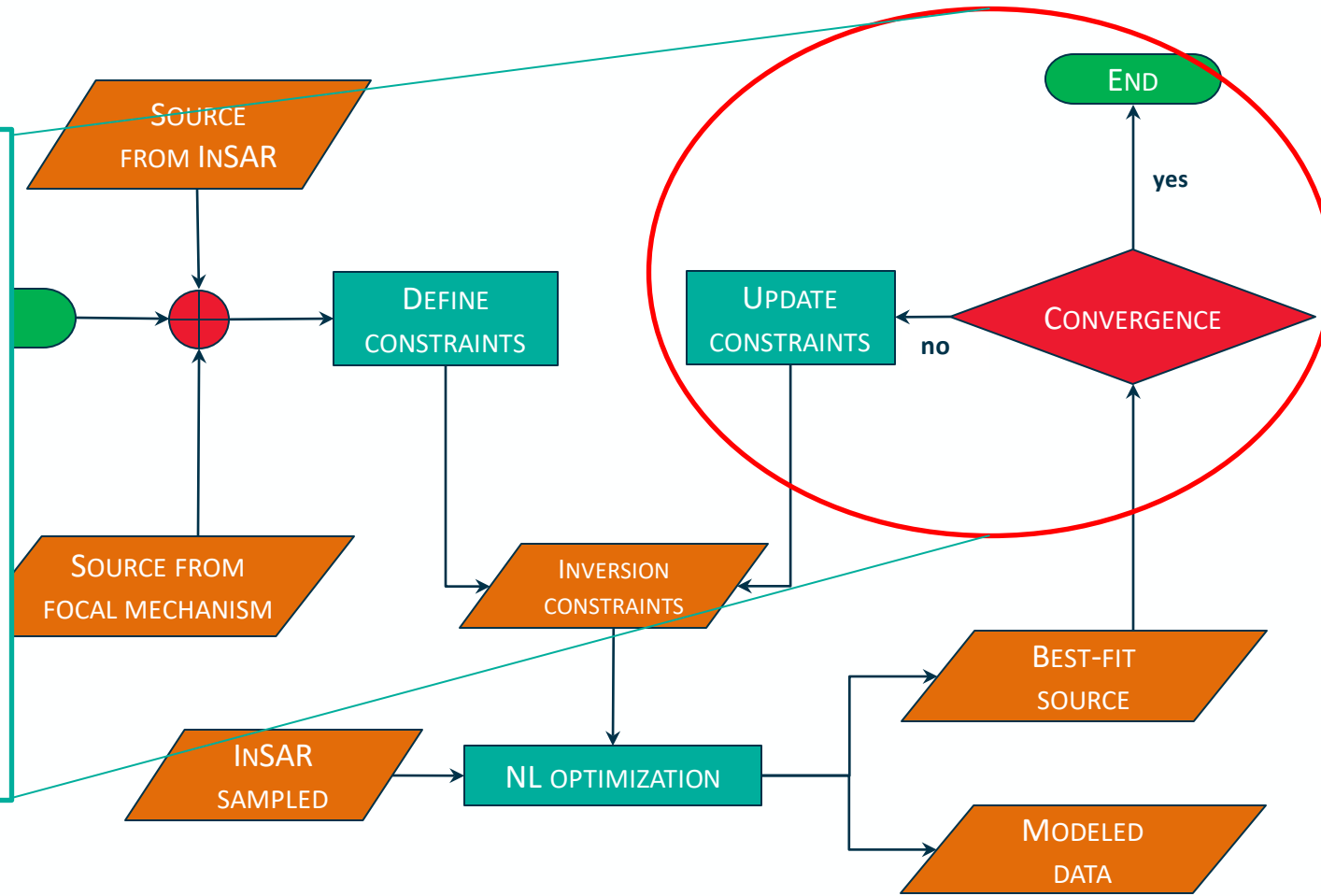
(a) from Atzori et al. (2019) <https://doi.org/10.1016/j.rse.2019.1114>

(b) William and Wedge (1998) <https://doi.org/10.1029/98GL01136>

# Automatic Non-Linear Inversion

## criteria to define the best fit source

1. all the parameters not constrained have best-fit values within their minimum/maximum ranges (corresponds to a successful non-linear optimization).
2. the direction of the slip vector, in the 3D space, different from that of the focal mechanism (more than  $55^\circ$ , by default)
3. the maximum number of iterations is reached (30, by default).



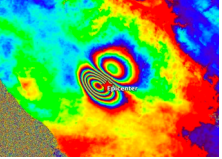
(a) from Atzori et al. (2019) <https://doi.org/10.1016/j.rse.2019.111461>

(b) William and Wedge (1998) <https://doi.org/10.1029/98GL01136>

# Automatic Processing Chain Implementation



EPOSAR Service TCS  
Satellite Data



Goal of the linear inversion is to retrieve the distribution of the shear dislocation over the fault plane identified by non-linear inversion.



Area definition  
Pair selection  
Data Sampling

inversion setup  
non-linear optimization  
convergence test  
setup update / end

source extension/subdivision  
damping definition  
 $d = Gm$  design  
 $G^{-1}$  calculation

source validation



Focal Mechanism to Define area

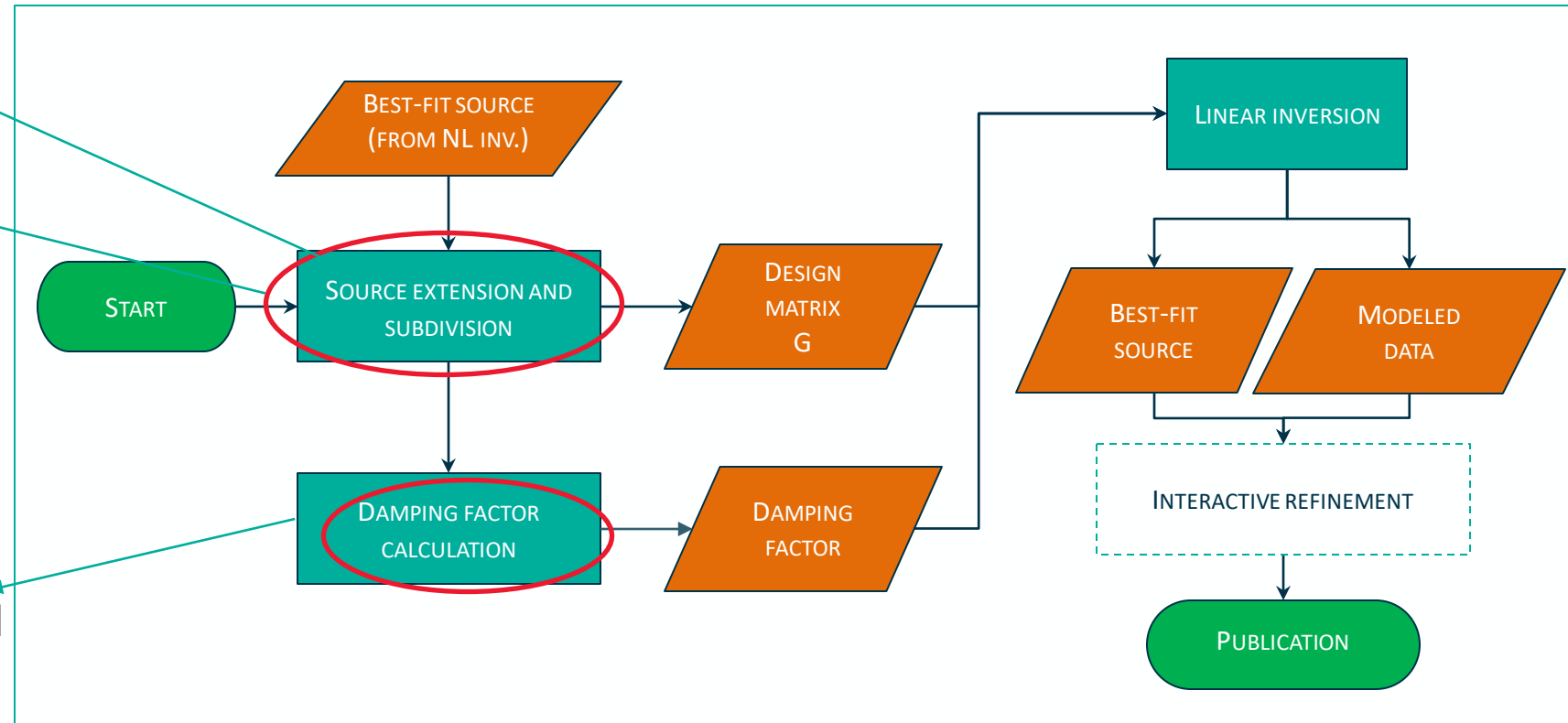


# Automatic Linear Inversion

Goal of the linear inversion is to retrieve the distribution of the shear dislocation over the fault plane identified by non-linear inversion.

The extension (length and width) NL source.

The fault plane subdivision into a number of patches (own slip value after the linear inversion).



$\mathbf{d} = \mathbf{Gm}$  linear system

$$\mathbf{m}^{\text{est}} = [\mathbf{G}^T \mathbf{G} + \epsilon^2 \mathbf{W}_m]^{-1} \mathbf{G}^T \mathbf{d} = \mathbf{G}^{-g} \mathbf{d}$$

$\epsilon$  strength of the smoothing

(automatic algorithm developed)

$\mathbf{m}$  is the vector of slip values,

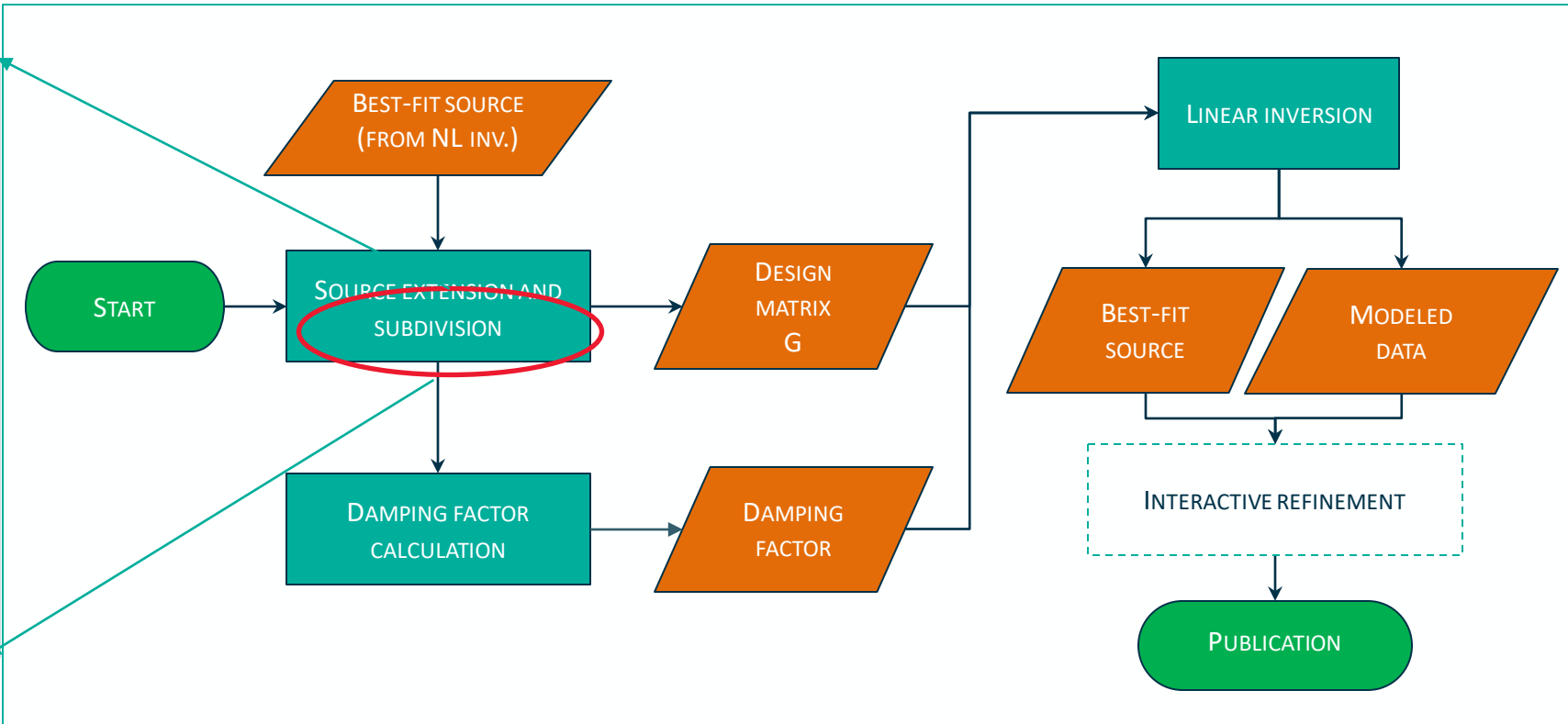
$\mathbf{d}$  is the vector of observations

$\mathbf{G}$  the design matrix based on the same dislocation model in an elastic half-space (Okada, 1985) used in the non-linear optimization.

# Automatic Linear Inversion

Goal of the linear inversion is to retrieve the distribution of the shear dislocation over the fault plane identified by non-linear inversion.

1. the longest between length and width is subdivided number of patches (30, by default)
2. the patch dimension is rounded to a multiple of hundreds/thousands of meters
3. the number of patches in the other dimension is calculated
4. final width and length are adjusted to be multiple of the patch size.



# Automatic Linear Inversion



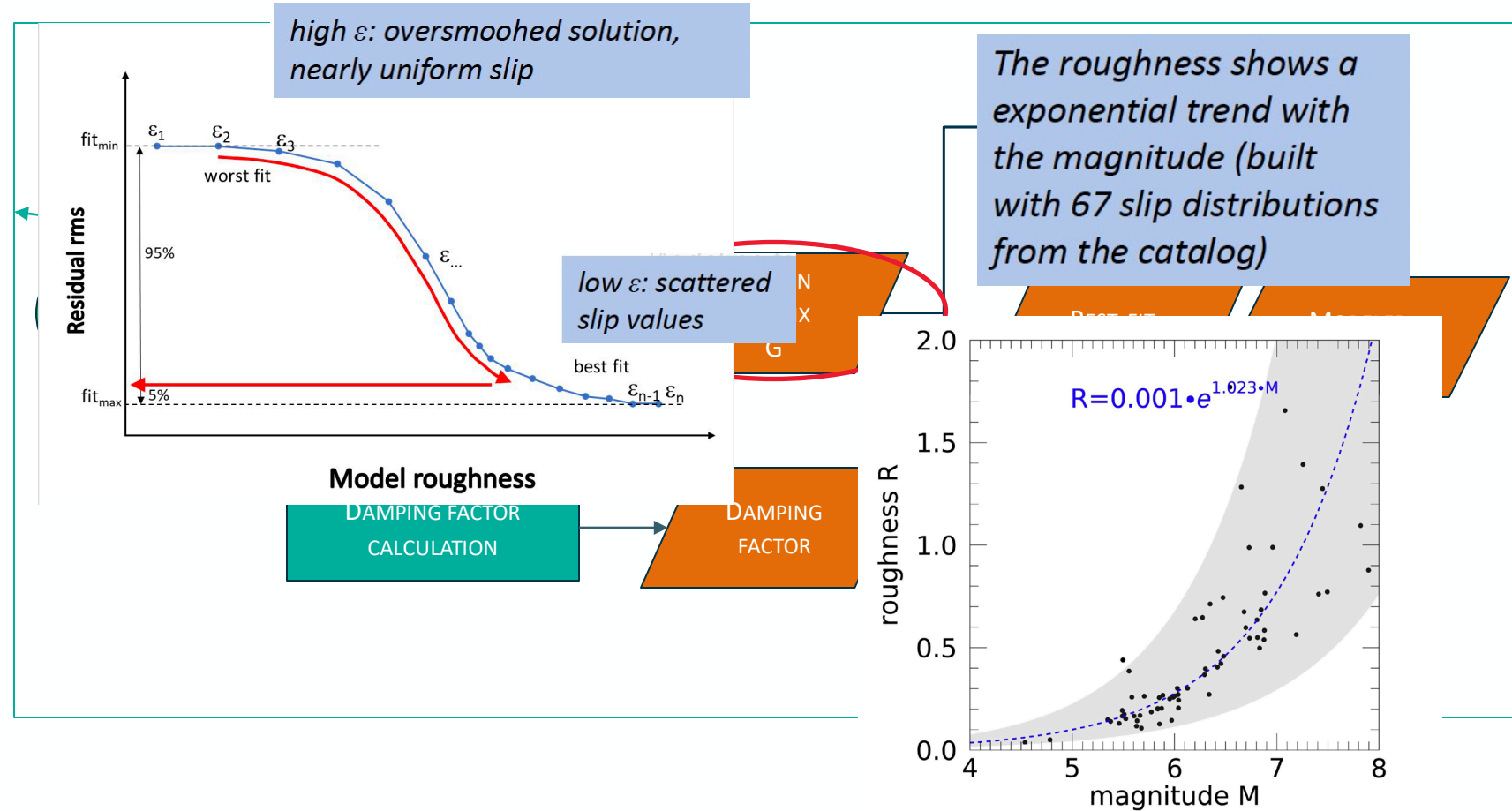
Goal of the linear inversion is to retrieve the distribution of the shear dislocation over the fault plane identified by non-linear inversion.

$$\mathbf{m}^{\text{est}} = [\mathbf{G}^T \mathbf{G} + \epsilon^2 \mathbf{W}_m]^{-1} \mathbf{G}^T \mathbf{d} = \mathbf{G}^{-1} \mathbf{d}$$

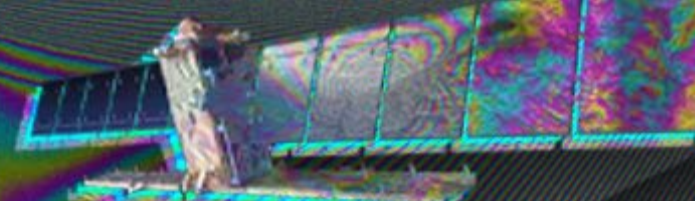
G = num of inversion points / patch subdivision

$\epsilon$  strength of the smoothing

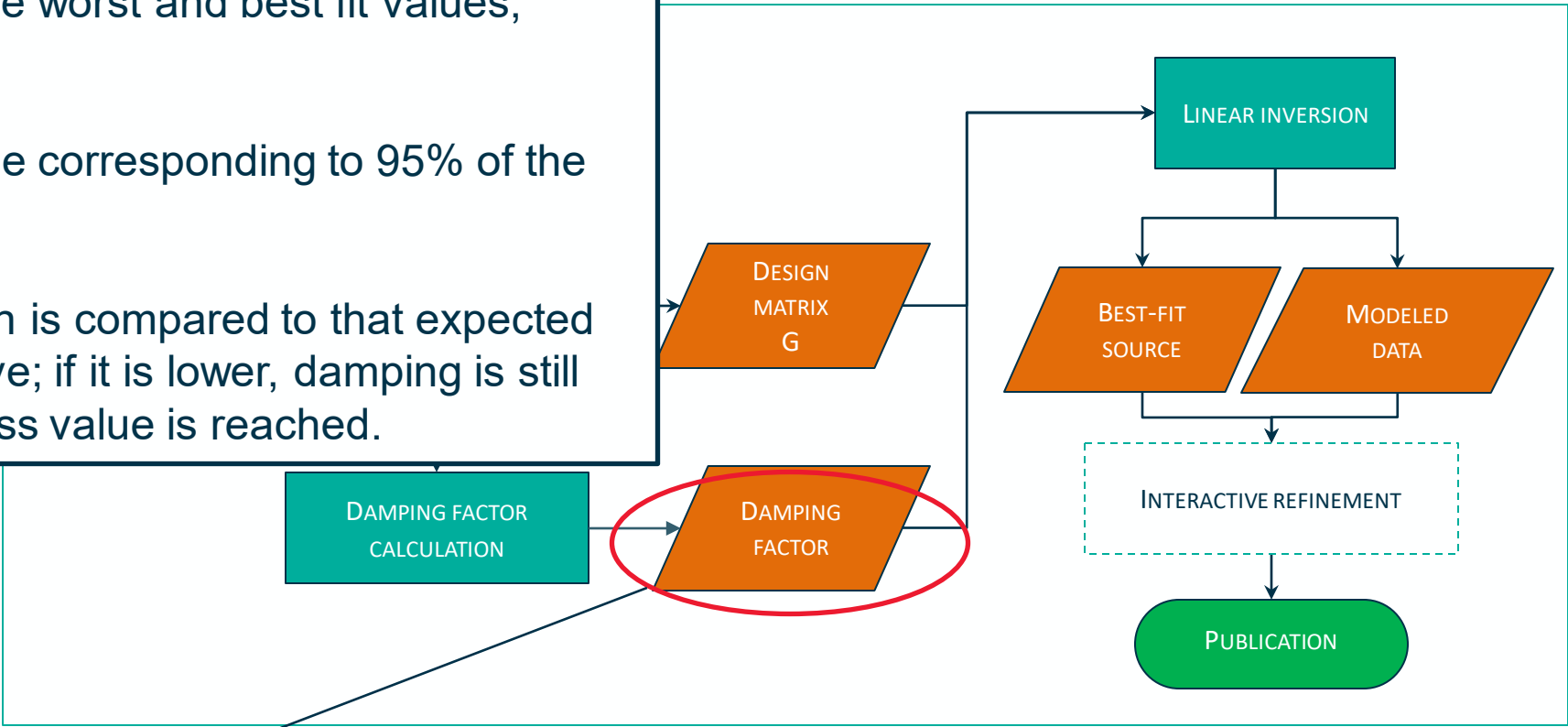
(automatic algorithm developed)



# Automatic Linear Inversion



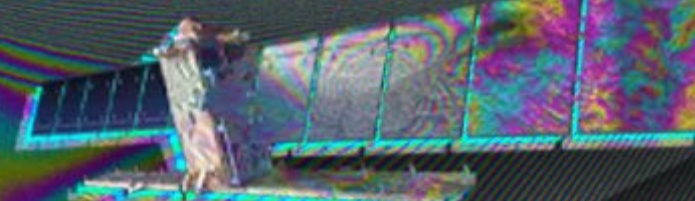
1. a data fit vs. model roughness curve is calculated to define, for the specific event, fitmin and fitmax, i.e. the worst and best fit values, respectively.
2. the damping factor is set to the value corresponding to 95% of the fitmin-fitmax interval
3. the roughness of this slip distribution is compared to that expected from the roughness vs magnitude curve; if it is lower, damping is still decreased until the expected roughness value is reached.



$\epsilon$  strength of the smoothing  
(automatic algorithm developed)



# Automatic Linear Inversion



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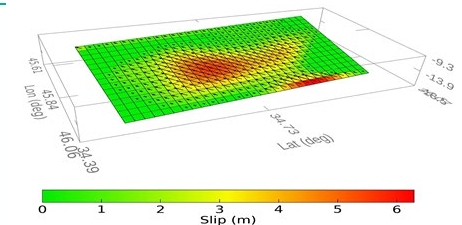
$G$  = num of inversion points / patch subdivision

$\epsilon$  strength of the smoothing

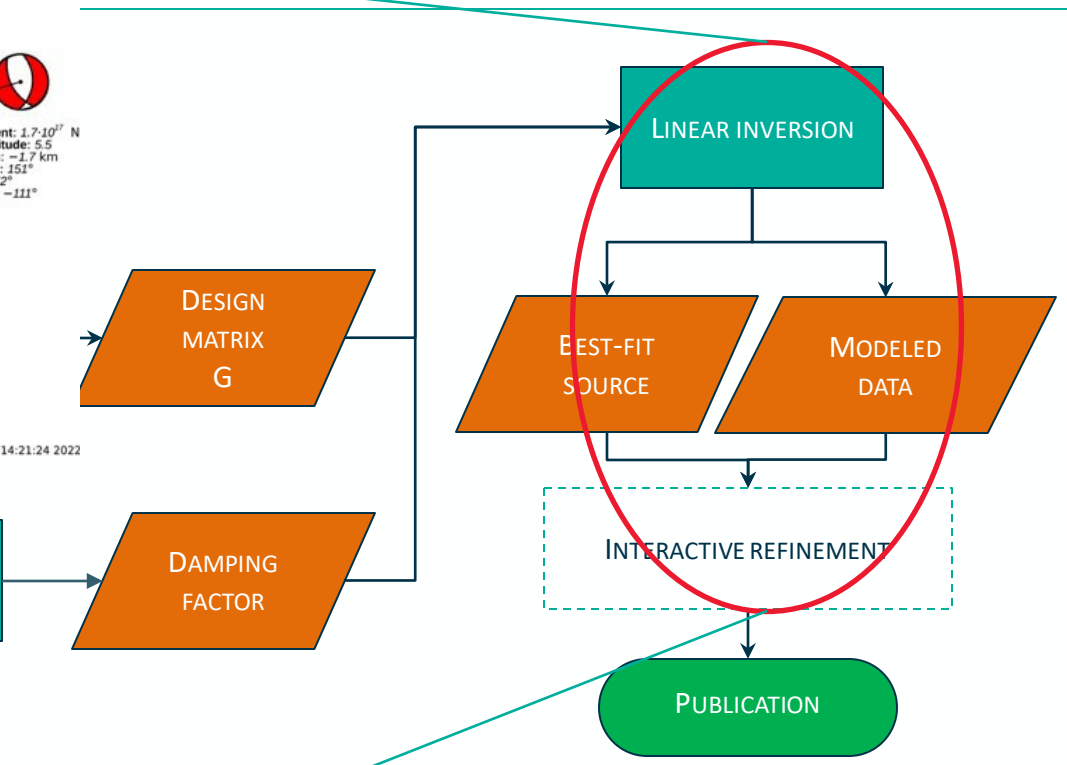
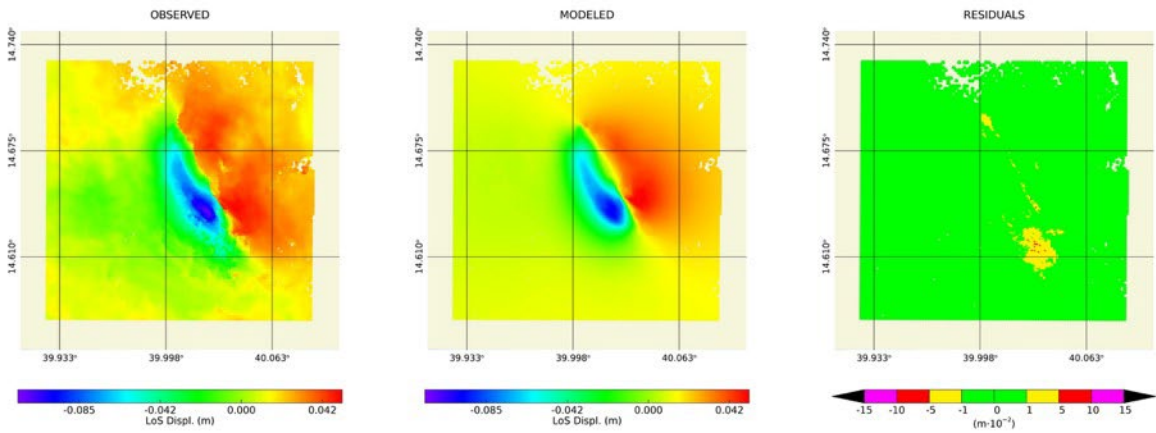
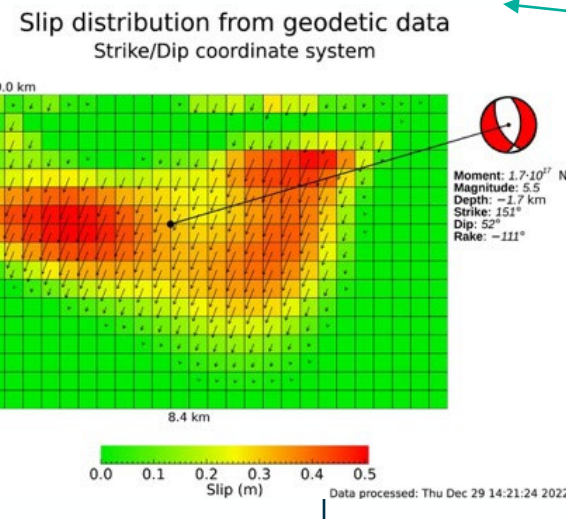
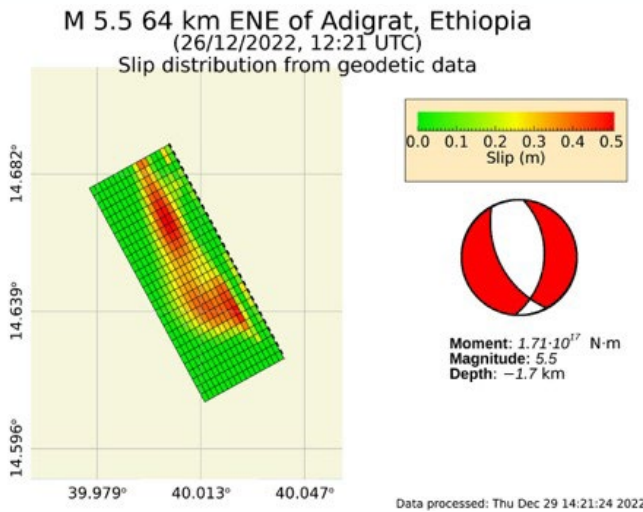
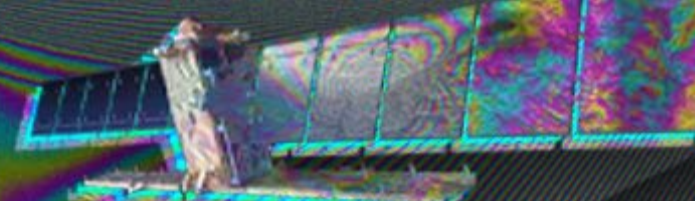
(automatic algorithm developed)



Array of slip vector

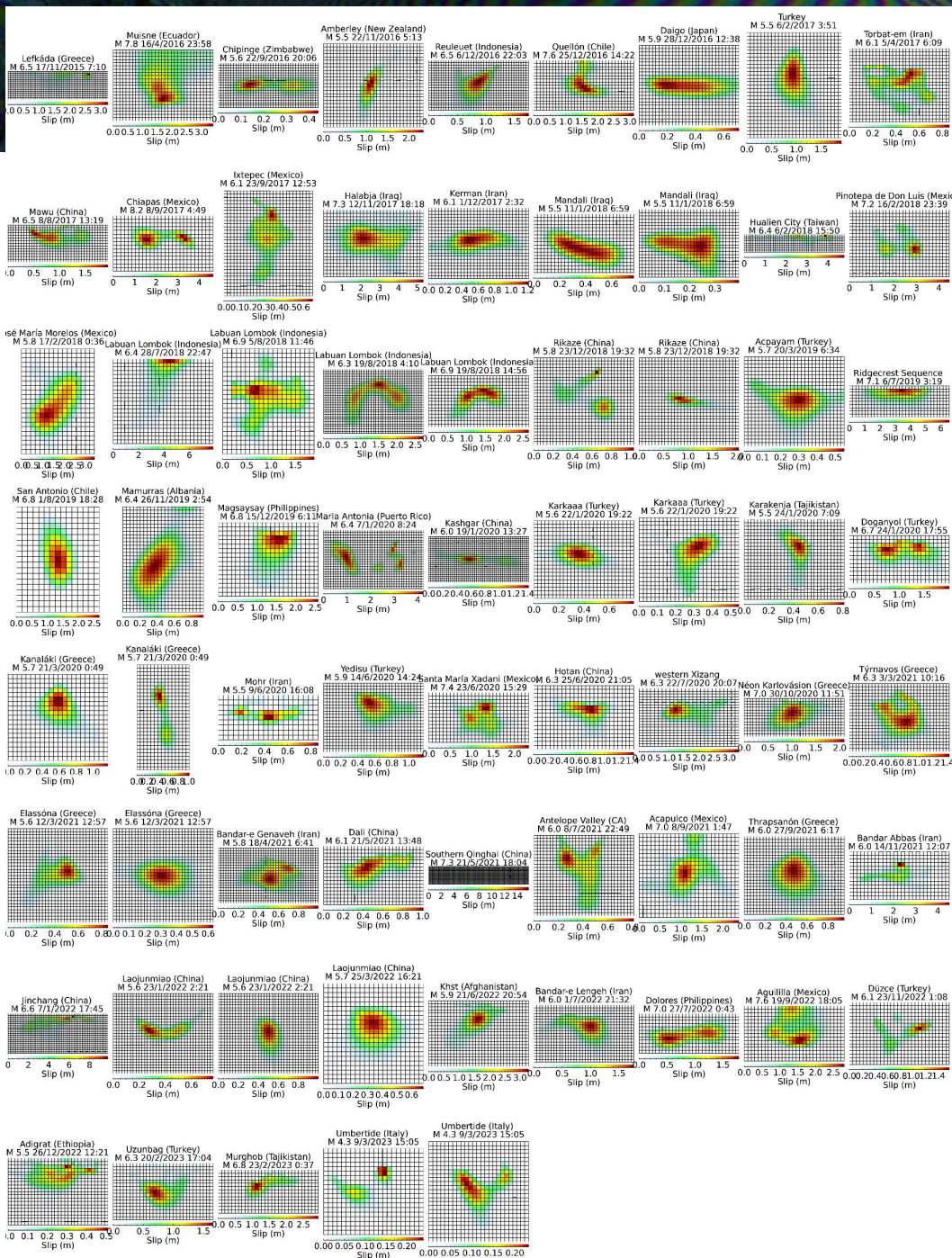


# Automatic Linear Inversion

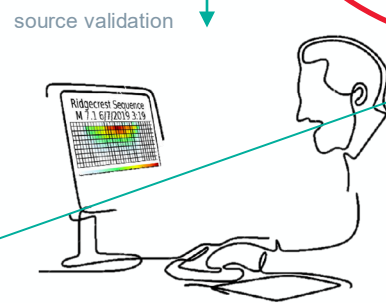


a completely automatic and unsupervised result can not be shared with the scientific community without any validation

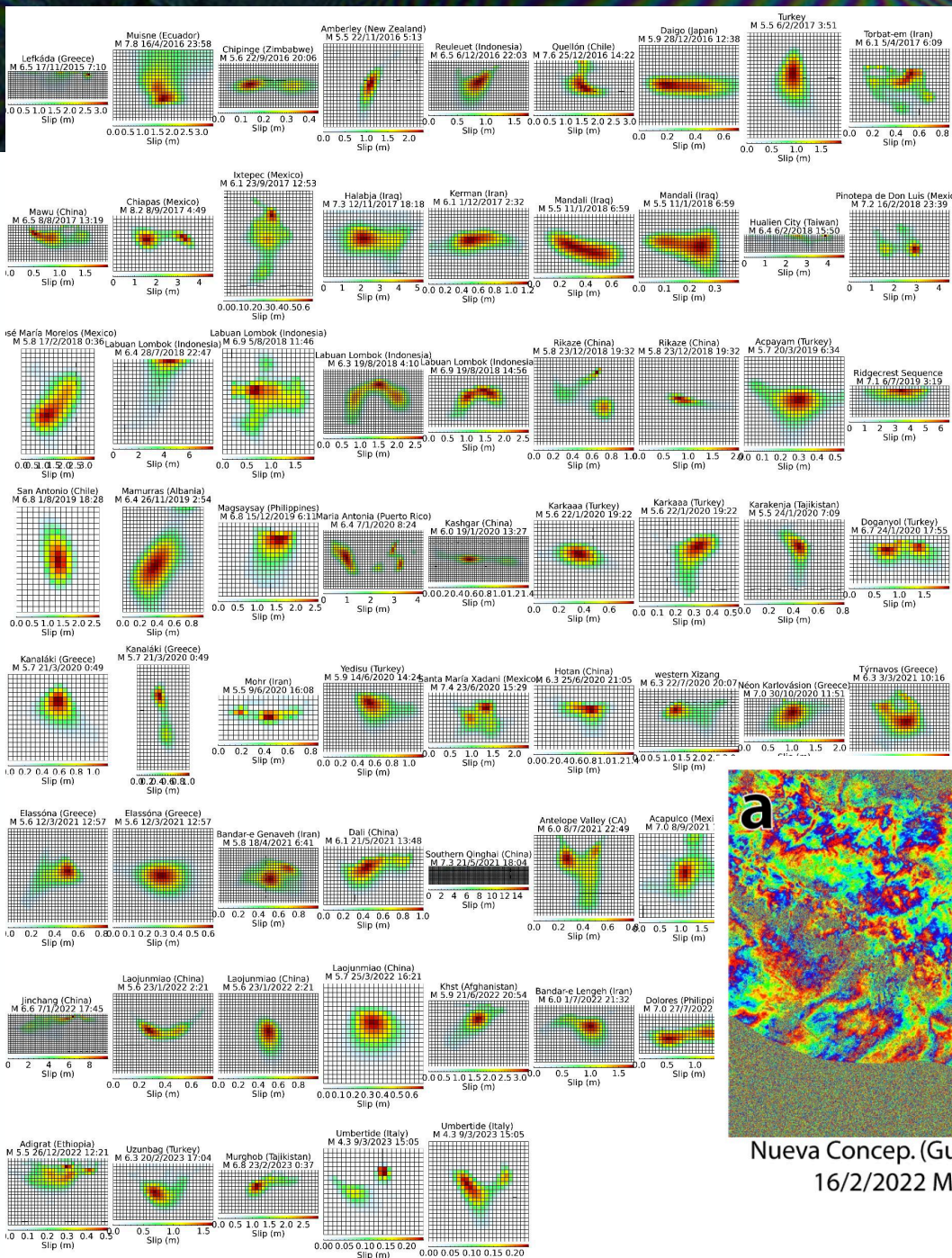
# Chain Implementation



99 Earthquakes tested (5.5 – 8.2 mw) and small magnitude 4.5 earthquake occurred near Umbertide (Italy).



# Chain Implementation



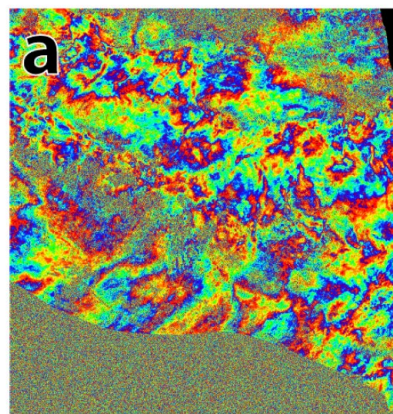
a). 16 earthquakes failed (not visible coseismic pattern).

b). 6 cases with coseismic signal was very small.

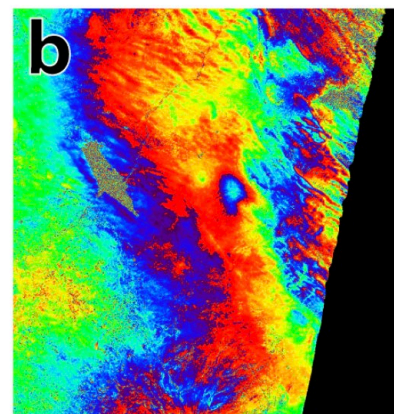
c). 6 cases with rupture of different fault segments (Hawaiian events or Amberley earthquake New Zealand).

d). 11 cases, modelling failed because the displacement maps were affected by strong decorrelation.

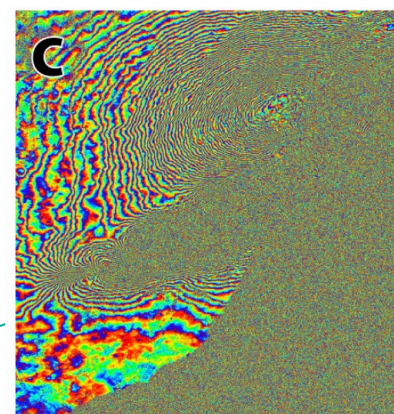
In 60 cases the modeling process successfully ended with the retrieval of a reliable slip distribution.



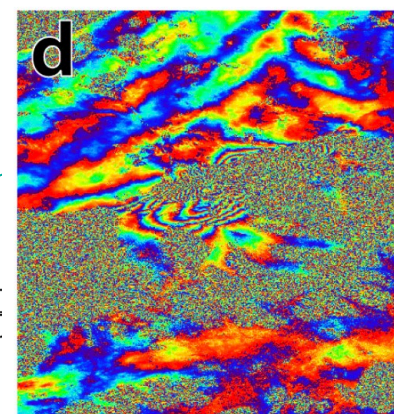
Nueva Concep. (Guatemala)  
16/2/2022 M 6.2



Sarpol-e Zahab (Iran)  
6/1/2019 M 5.6



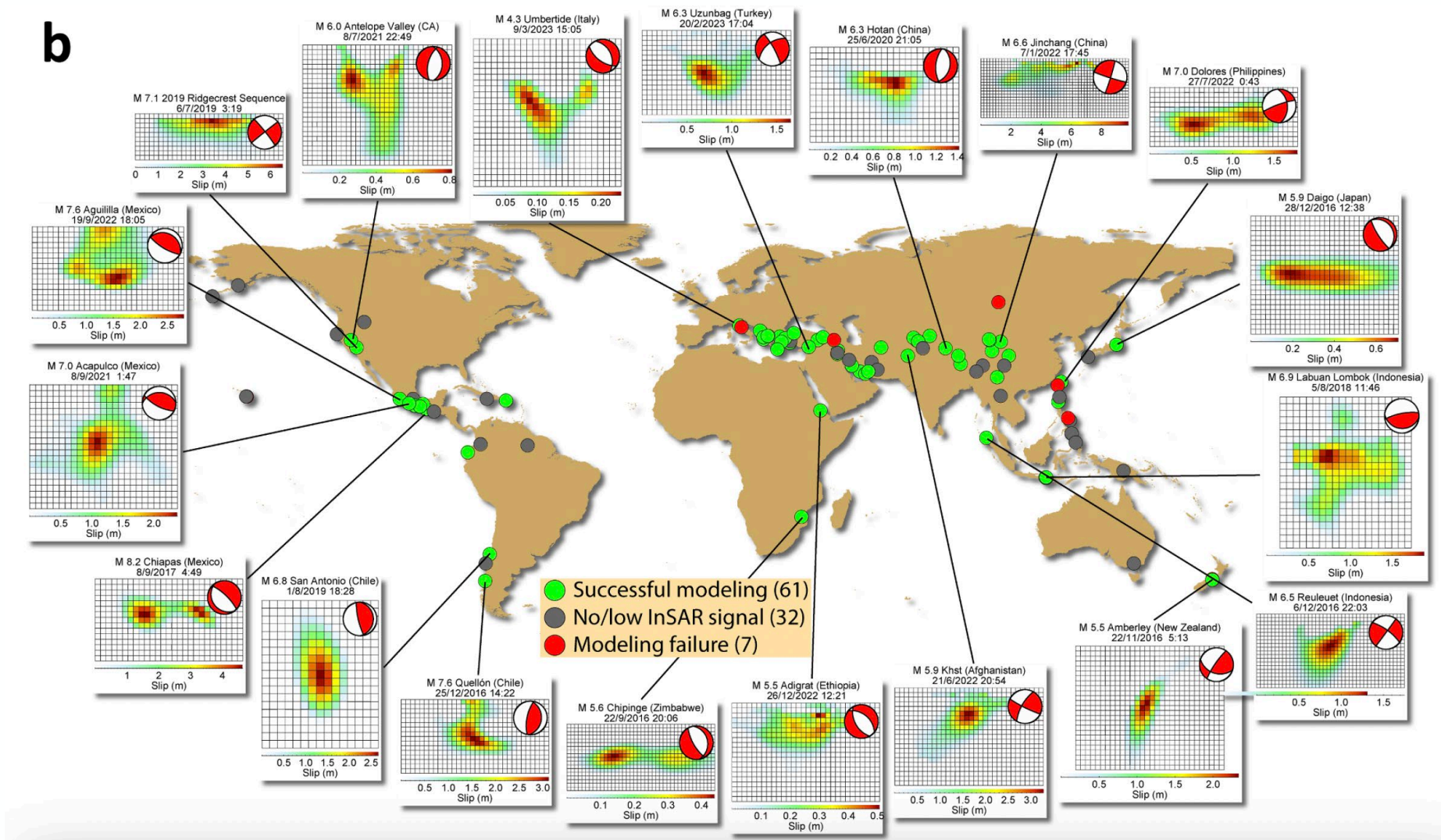
Amberley (New Zealand)  
13/11/2016 M 7.8



Unalaska (Alaska)  
22/1/2022 M 6.2



# Experimental Results (100 Earthquakes)



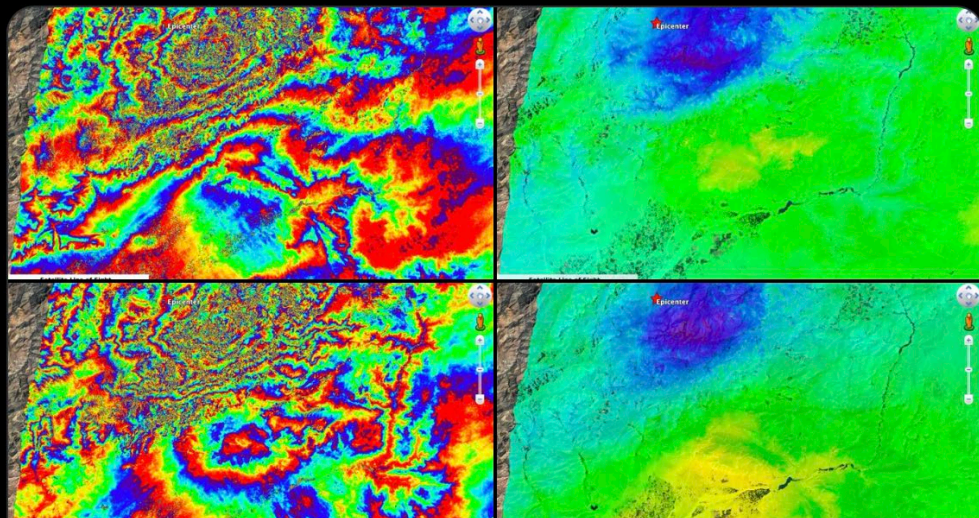
### Coseismic interferograms for Morocco Earthquake Descending Orbit

154



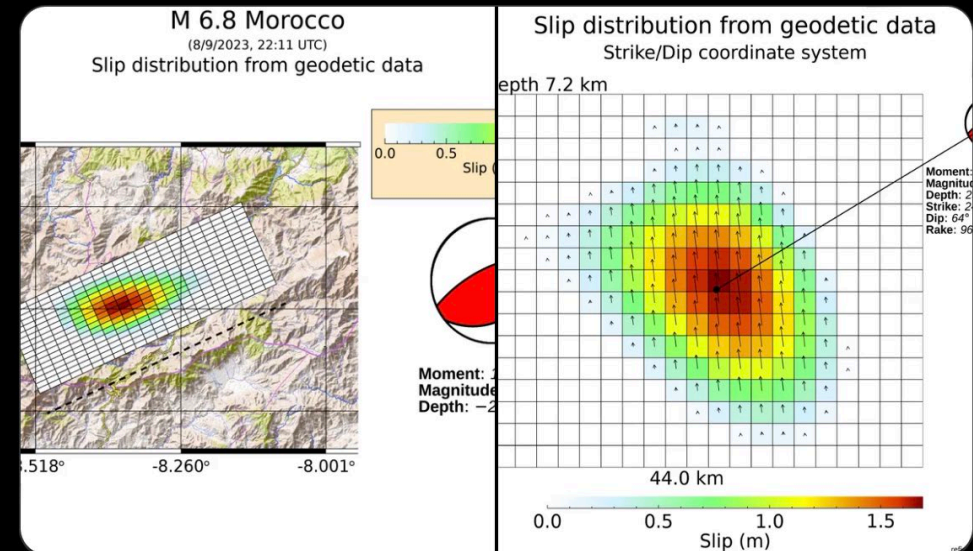
Fernando Monterroso  
@maferp\_13

The #Sentinel1 co-seismic interferogram and LOS Displacement map of the recent #MoroccoEarthquake (Mw 6.8), You can find this and other DInSAR co-seismic products on the @EPOSeu geoportal @CnrIrea @FraxInSAR @claudiodeluca @SimoneAtzori73 @dott109 Traducir post



Simone Atzori  
@SimoneAtzori73

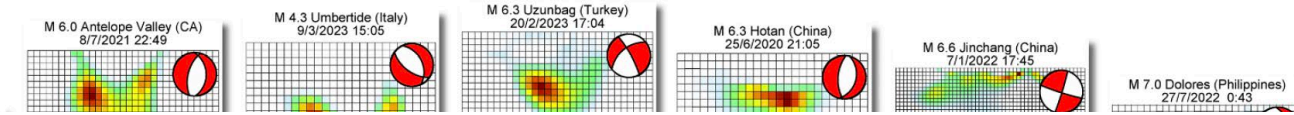
Source model of the M 6.7 #moroccoearthquake derived from inversion of #InSAR data (see cited tweet).  
More info, model and sampled InSAR data for download (shapefile) here: [terremoti.ingv.it/en/finitesourc..](http://terremoti.ingv.it/en/finitesourc..) ("finite source" tab)  
With @antandre71 @maferp\_13 @FraxInSAR @dott109 Traducir post



# Experimental Results (100 Earthquakes)



b



International Journal of Applied Earth Observation and Geoinformation 123 (2023) 103445

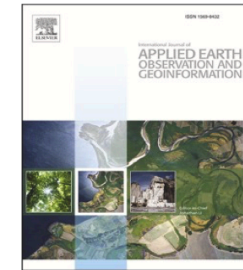


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journal homepage: [www.elsevier.com/locate/jag](http://www.elsevier.com/locate/jag)

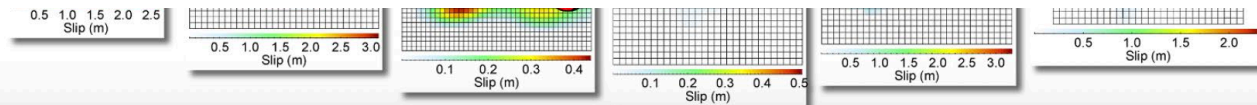


## Automatic seismic source modeling of InSAR displacements

Simone Atzori <sup>a,\*</sup>, Fernando Monterroso <sup>b</sup>, Andrea Antonioli <sup>a</sup>, Claudio De Luca <sup>b</sup>, Nikos Svigkas <sup>a</sup>, Francesco Casu <sup>b</sup>, Michele Manunta <sup>b</sup>, Matteo Quintiliani <sup>a</sup>, Riccardo Lanari <sup>b</sup>

<sup>a</sup> *Istituto Nazionale di Geofisica e Vulcanologia, Rome, Italy*

<sup>b</sup> *Istituto per il Rilevamento Elettromagnetico dell'Ambiente, Naples, Italy*



- We create a instrument for a quick and robust identification of the source parameters after an earthquake
- We developed an active service with future  $M > 5.5$  events at global scale
- Extension of the catalog to all the sources detected with InSAR since 2015 (Sentinel-1)
- Consolidation of formats and metadata within EPOS, TCS-SATD to be published available for the scientific community
- System preparation for incoming SAR missions (NISAR, NASA-ISRO)
- Extension to multiple source modeling with AI



# Thank you!



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[simone.atzori@ingv.it](mailto:simone.atzori@ingv.it)



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@SimoneAtzori73

Paper published 18 August 2023



<https://www.sciencedirect.com/science/article/pii/S1569843223002698>

The catalog of sources



<http://terremoti.ingv.it/finitesource>

The catalog EPOSAR service



<https://www.ics-c.epos-eu.org/>