

# PERFORMANCE ANALYSIS OF THE HARMONY MISSION FOR LAND APPLICATIONS: RESULTS FROM THE PHASE A STUDY

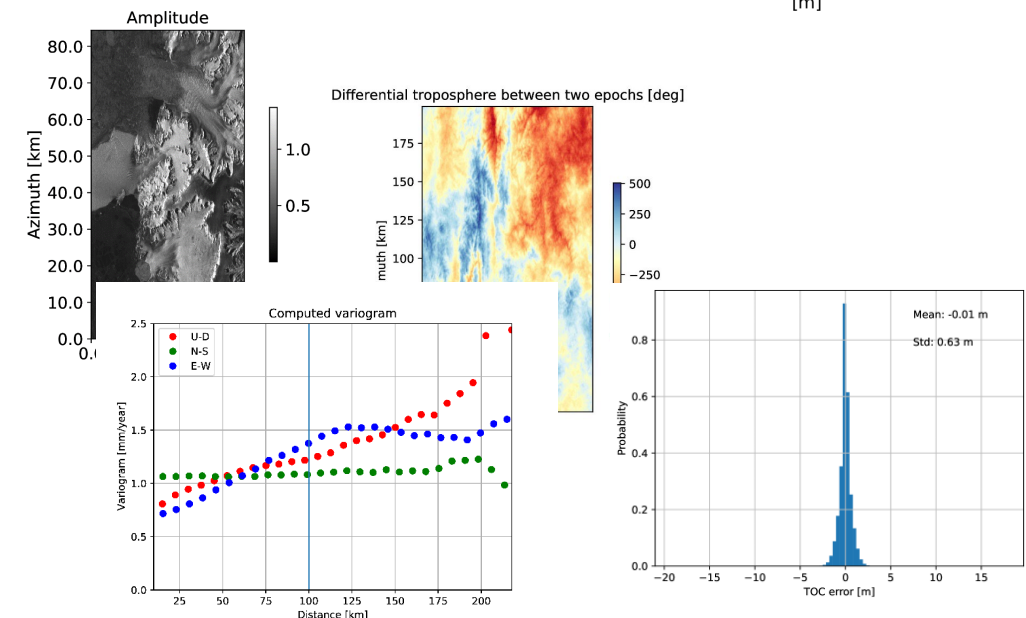
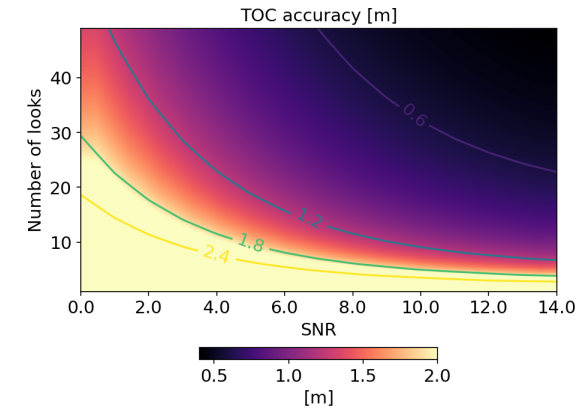
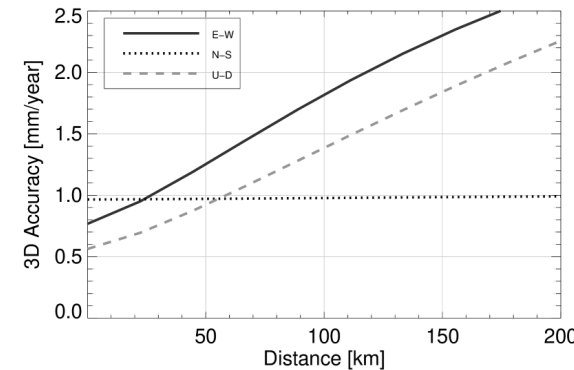
P. Prats-Iraola<sup>a</sup>, A. Pulella<sup>a</sup>, A. Benedikter<sup>a</sup>, A. Hooper<sup>b</sup>, J. Biggs<sup>c</sup>, A. Kääb<sup>d</sup>, B. Rabus<sup>e</sup>, T. Nagler<sup>f</sup>, H. Rott<sup>f</sup>, O. Pappas<sup>c</sup>, F. De Zan<sup>g</sup>, V. Navarro<sup>a</sup>, R. Brcic<sup>a</sup>, N. Sakar<sup>a</sup>, G. Martin del Campo<sup>a</sup>, S. Trumpf<sup>a</sup>, J. Kramp<sup>a</sup>, G. Fischer<sup>a</sup>, M. Rodriguez-Cassola<sup>a</sup>, P. Lopez-Dekker<sup>h</sup>, B. Rommen<sup>i</sup>



# Performance Evaluation for Harmony Land



- Goal: evaluate the performance for the TVD (3-D deformation) and TOC (topography change) products for both solid Earth and land ice
- Analytical performance models to compute the asymptotic performance (mostly based on existing literature)
- Numerical end-to-end simulations using as realistic as possible forward models, partially using real data (S1 reflectivity, covariance, atmospheric data, real clock realizations, etc.) including up to L2/L3 processing

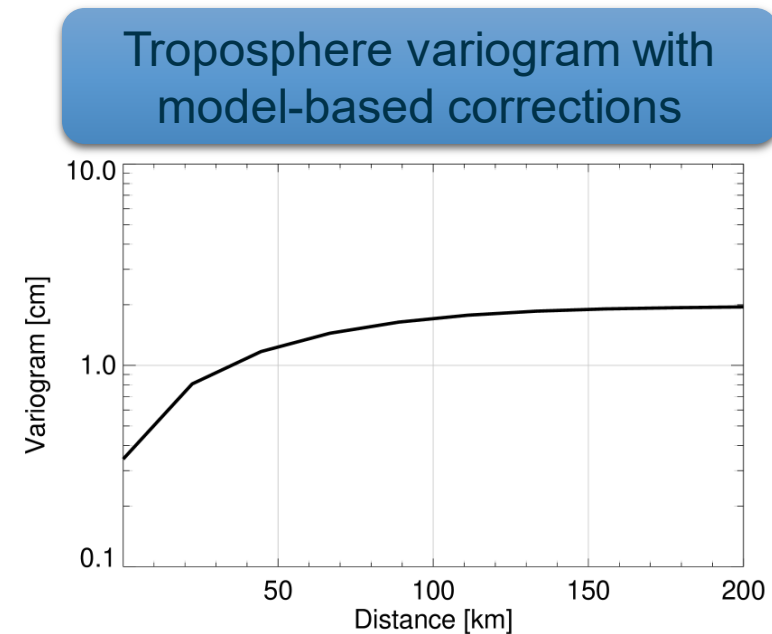
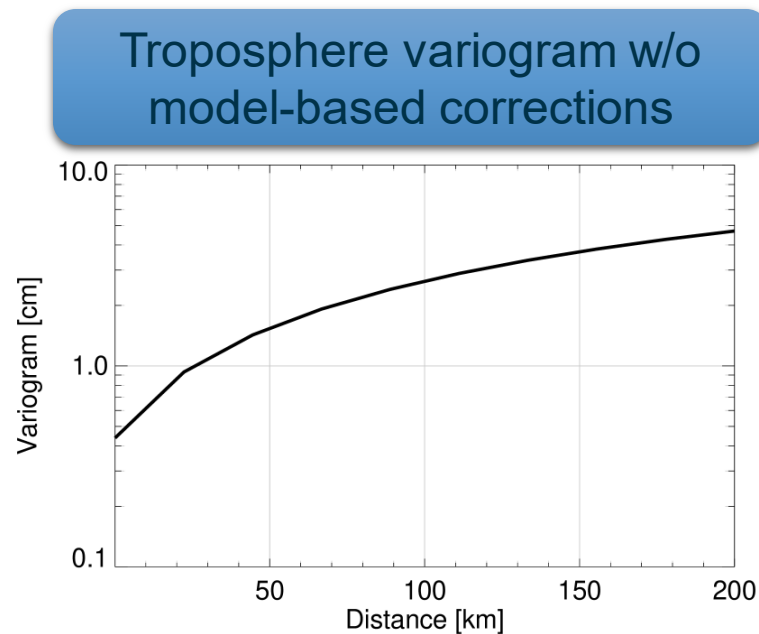


# Analytical Performance Models

# Analytical Product Performance Evaluation



- TVD (3-D Deformation) product performance based on literature [1] and updated to include 3 lines of sight + additional error sources (ionosphere, clock errors, baseline errors), as well as the different mission phases
- Usage of data-based model for troposphere (variograms)



# Analytical Product Performance Evaluation



Test Case	Description	Comment
Scenario #1	5 years Stereo	Ideal (for reference)
Scenario #2	Asc&Desc with Harmony (1 year XTI + 3 years STEREO + 1 year XTI)	Best N-S performance
Scenario #3	Only one configuration with Harmony	Worse N-S performance than scenario #2
Scenario #4	Asc&Desc with Harmony + 5 extra years Sentinel-1	Improved performance for E-W and vertical components

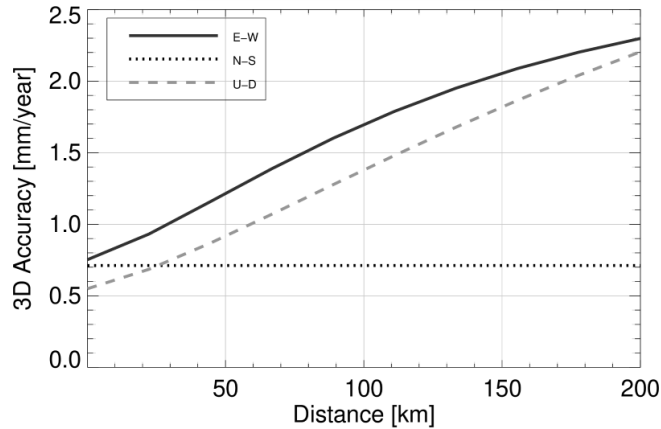
Relevant simulation parameters:

- Harmony-S1 along-track baseline: 350 km
- Temporal decorrelation: exponential model ( $\tau = 40$  days,  $\gamma_{\infty} = 0.2$ )
- Orbit inclination:  $12^{\circ}$
- Product resolution: 100 m x 100 m

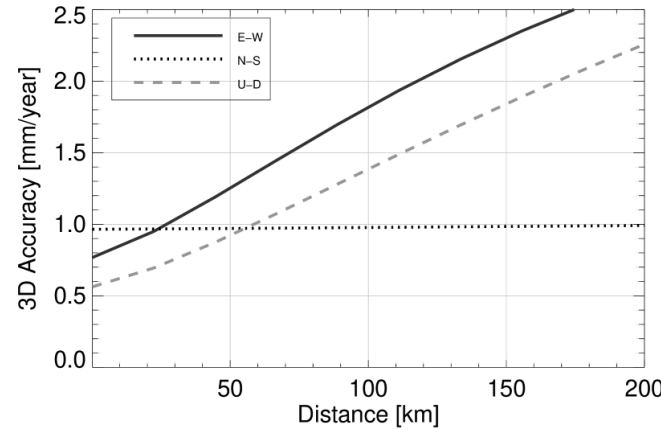
# Analytical Product Performance Evaluation



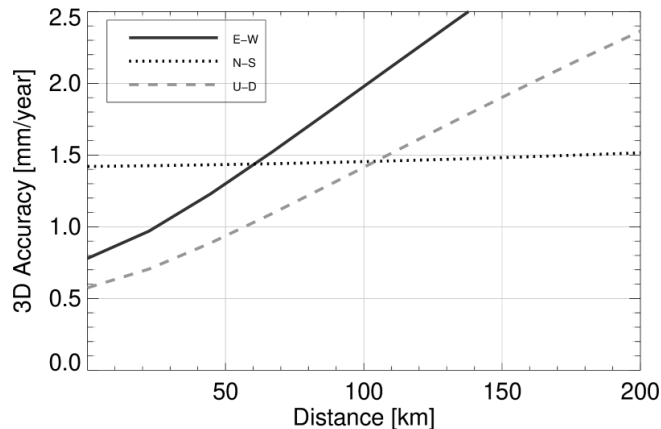
## Scenario #1



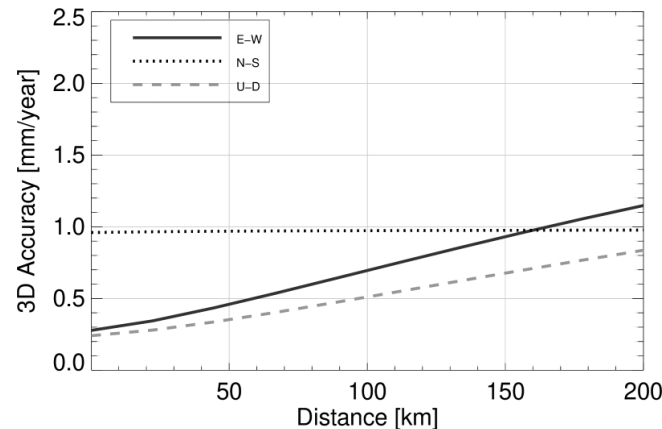
## Scenario #2



## Scenario #3



## Scenario #4



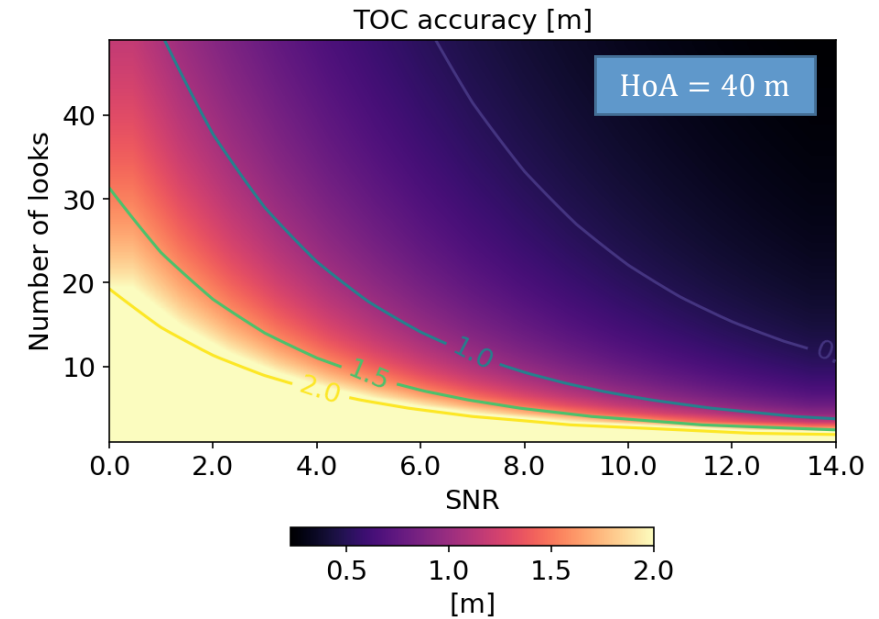
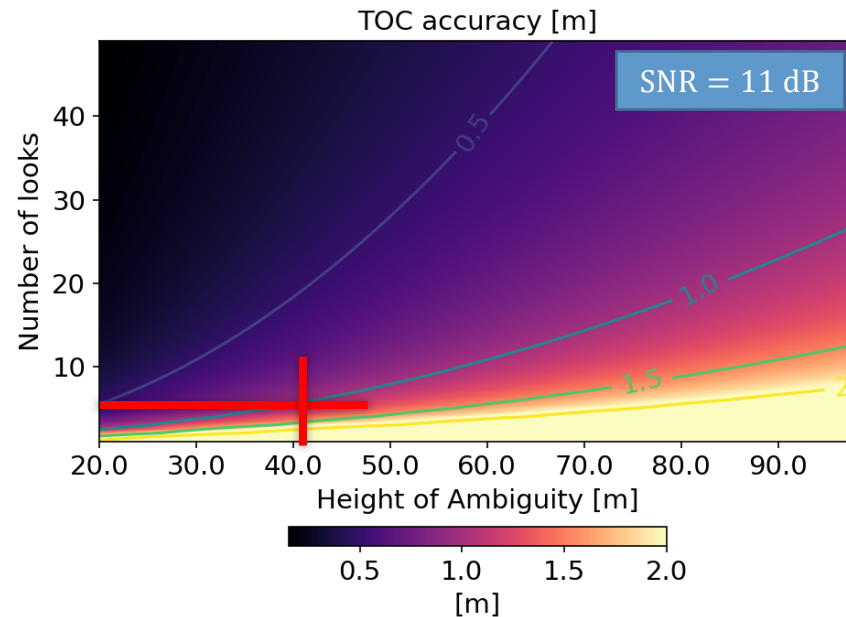
## Observations:

- N-S deformation almost independent of distance to reference point (high correlation of tropospheric signal among lines of sight)
- E-W and vertical performance can be improved by extending the time series with pre-Harmony Sentinel-1 acquisitions.
- Goal requirement (1 mm/yr @100 km) achieved in Scenario #4
- Threshold requirement (2 mm/yr @100 km) achieved in all scenarios

# Analytical Performance Evaluation



- TOC (Topography Change) product performance based on well-known InSAR performance equations [2]



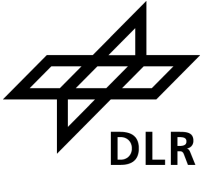
## Observations:

- Goal requirements of 1 m TOC accuracy at 30 m x 30 m (solid Earth) and 0.2 m/yr at 50 m x 50 m (land ice) are challenging
- Large baselines result in a more challenging phase unwrapping
- Averaging of consecutive DEMs might need to be assessed for each particular scenario

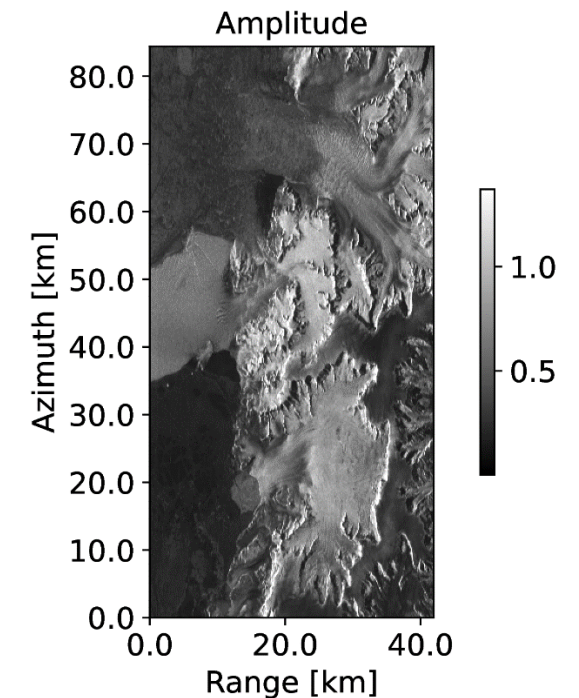
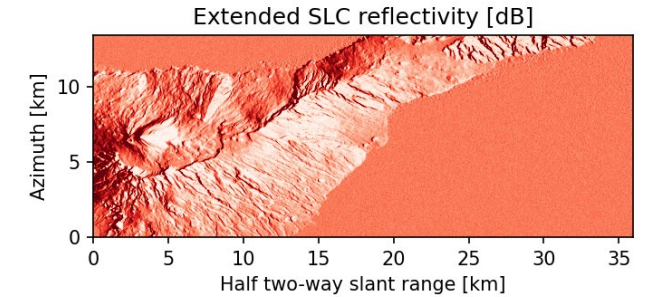
# End-to-End Simulations



# HEEPS/Terra – Overview



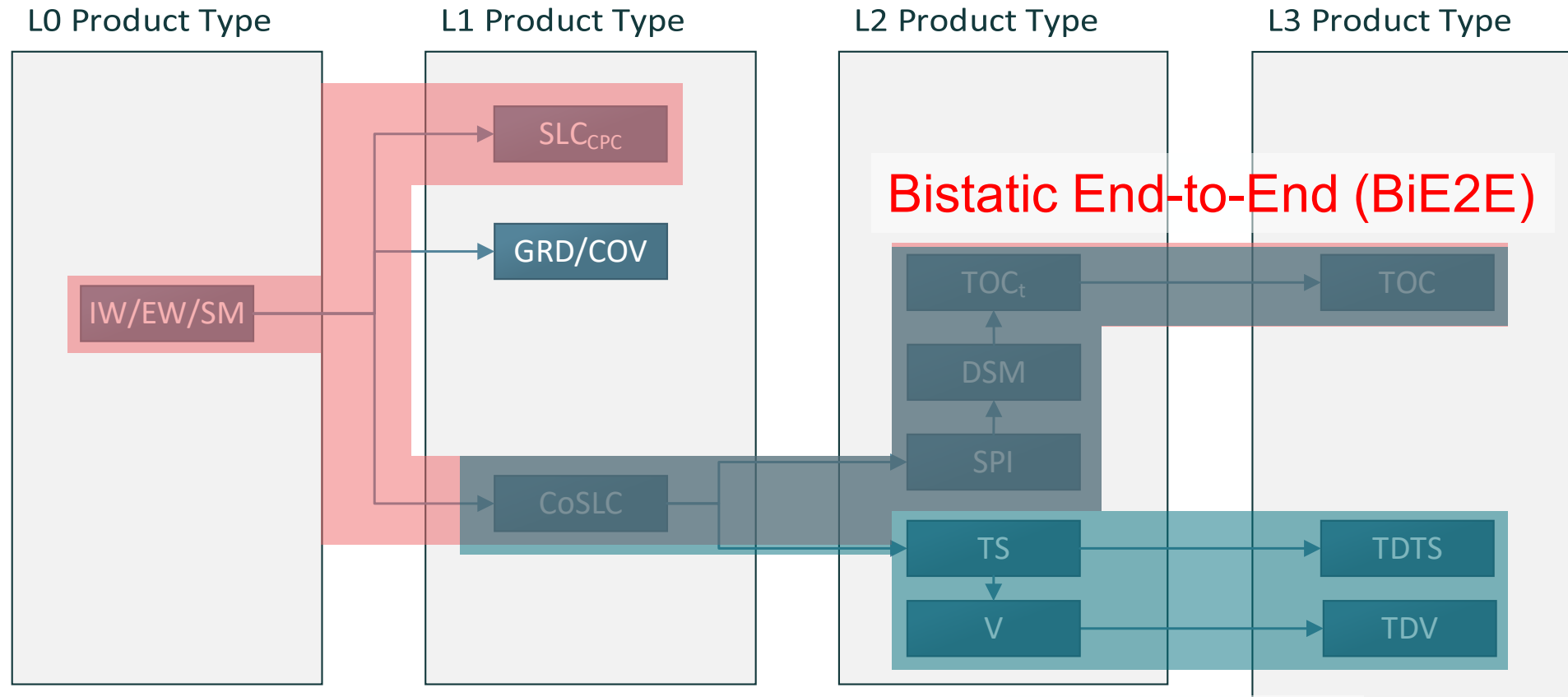
- HEEPS = Harmony End-to-End Performance Simulator
- Bistatic End-to-End (BiE2E) simulator
  - Builds on previous developments under ESA contract
  - Generates raw data
  - Includes L1&L2 processing
  - Simulation of XTI phase
- L1a Simulator
  - Extension of simulator developed during Phase 0
  - Generates L1a (single-look complex) images
  - Includes L2/L3 processing
  - Simulation of XTI and Stereo phases



# HEEPS/Terra – Overview



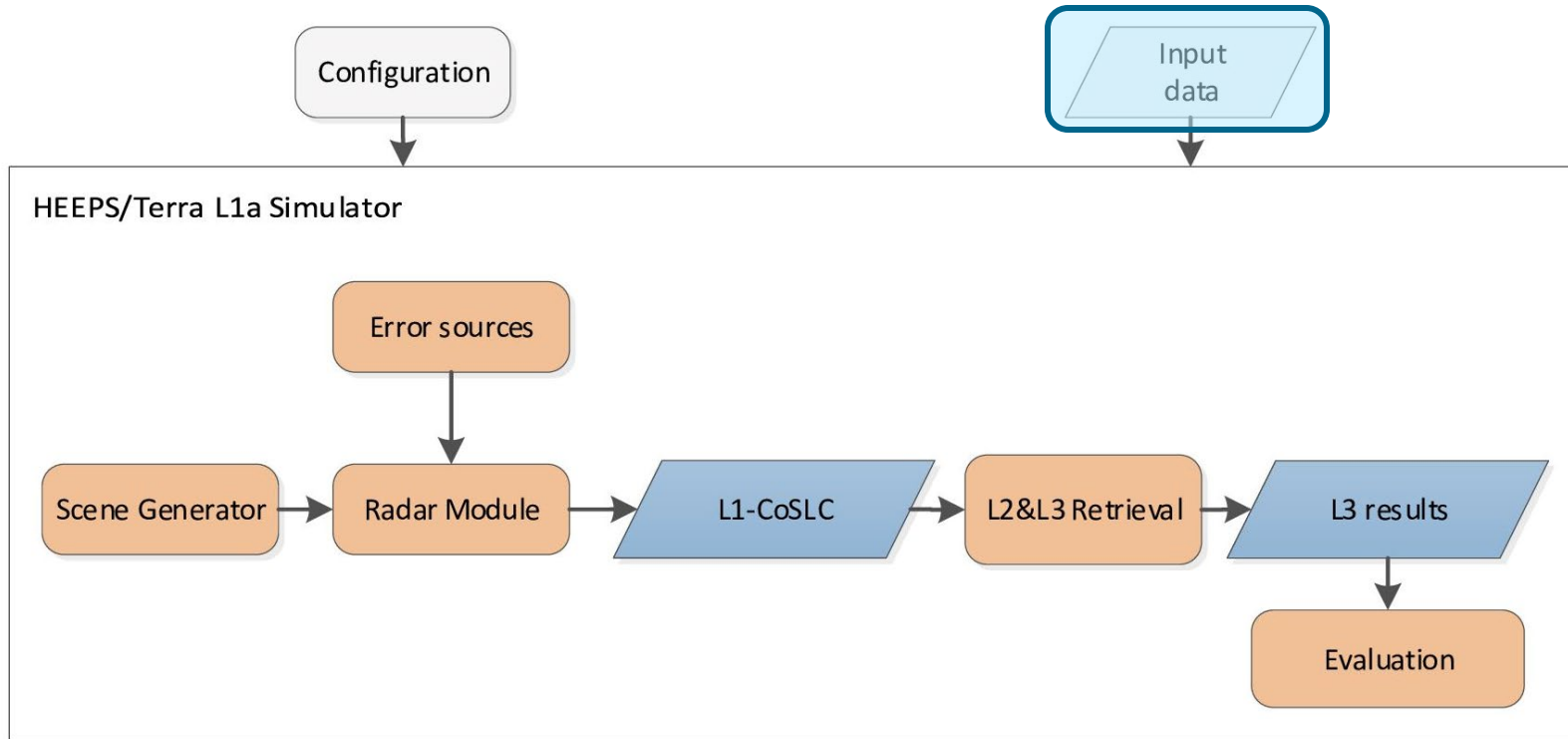
## Product tree for land applications



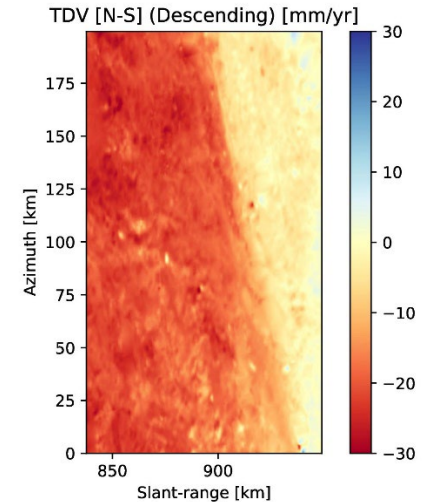
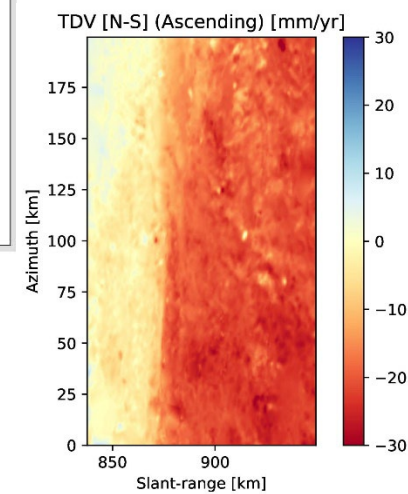
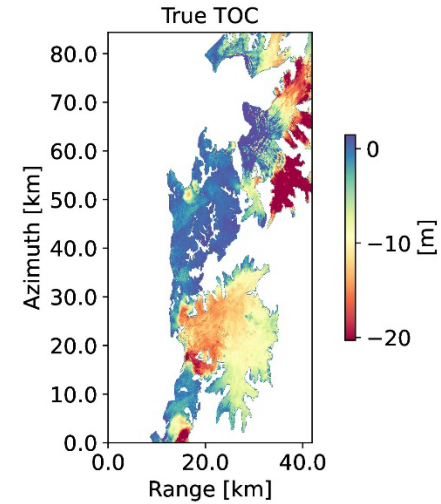
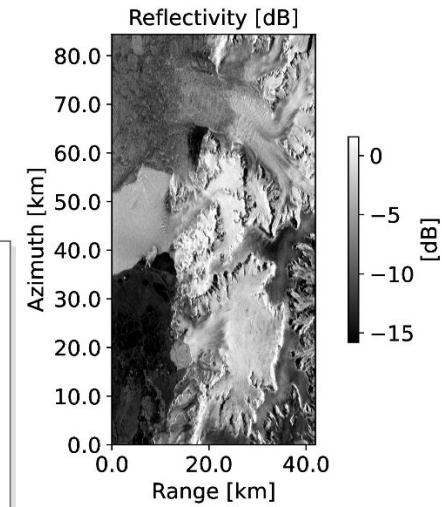
DSM: Digital Surface Model  
TOC: Topography Change  
TDV: 3-D Velocity Vectors  
TDTS: 3-D Time Series

L1a Simulator

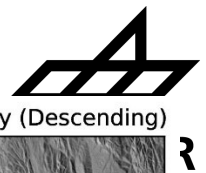
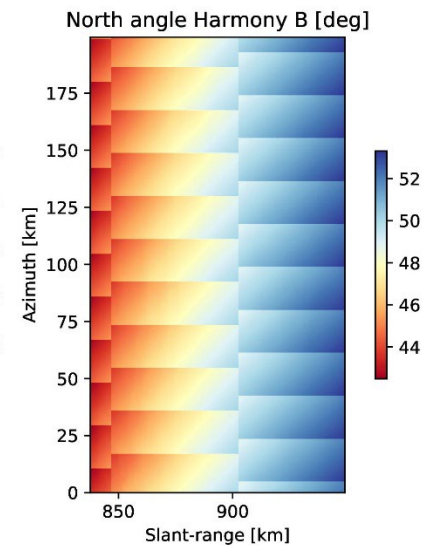
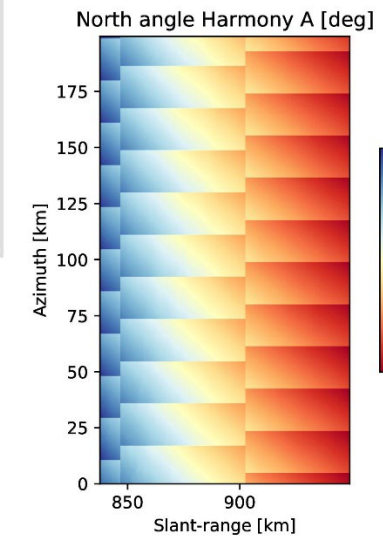
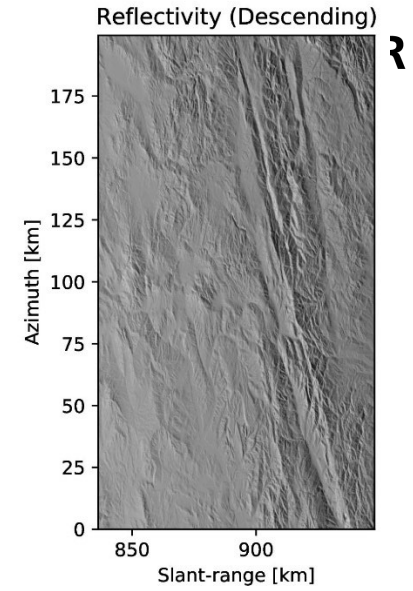
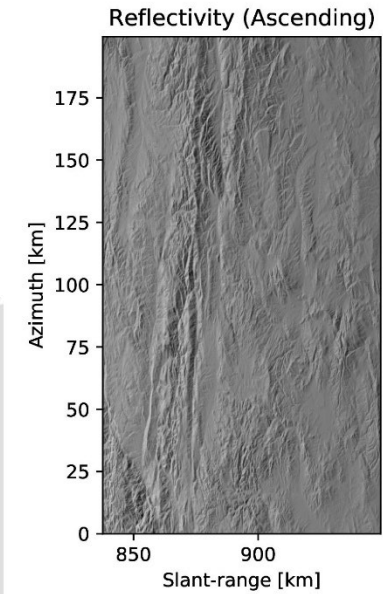
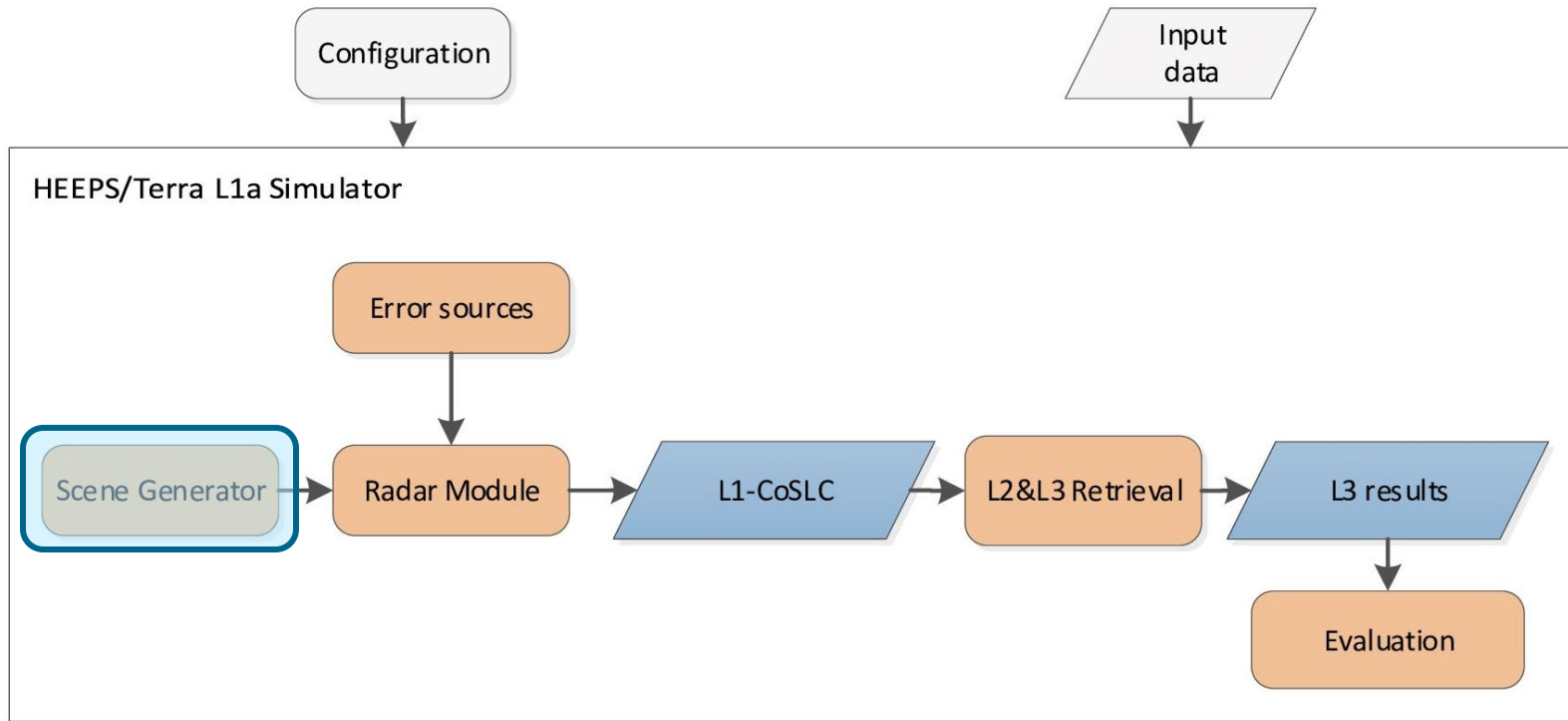
# HEEPS/Terra L1a Simulator – Architecture



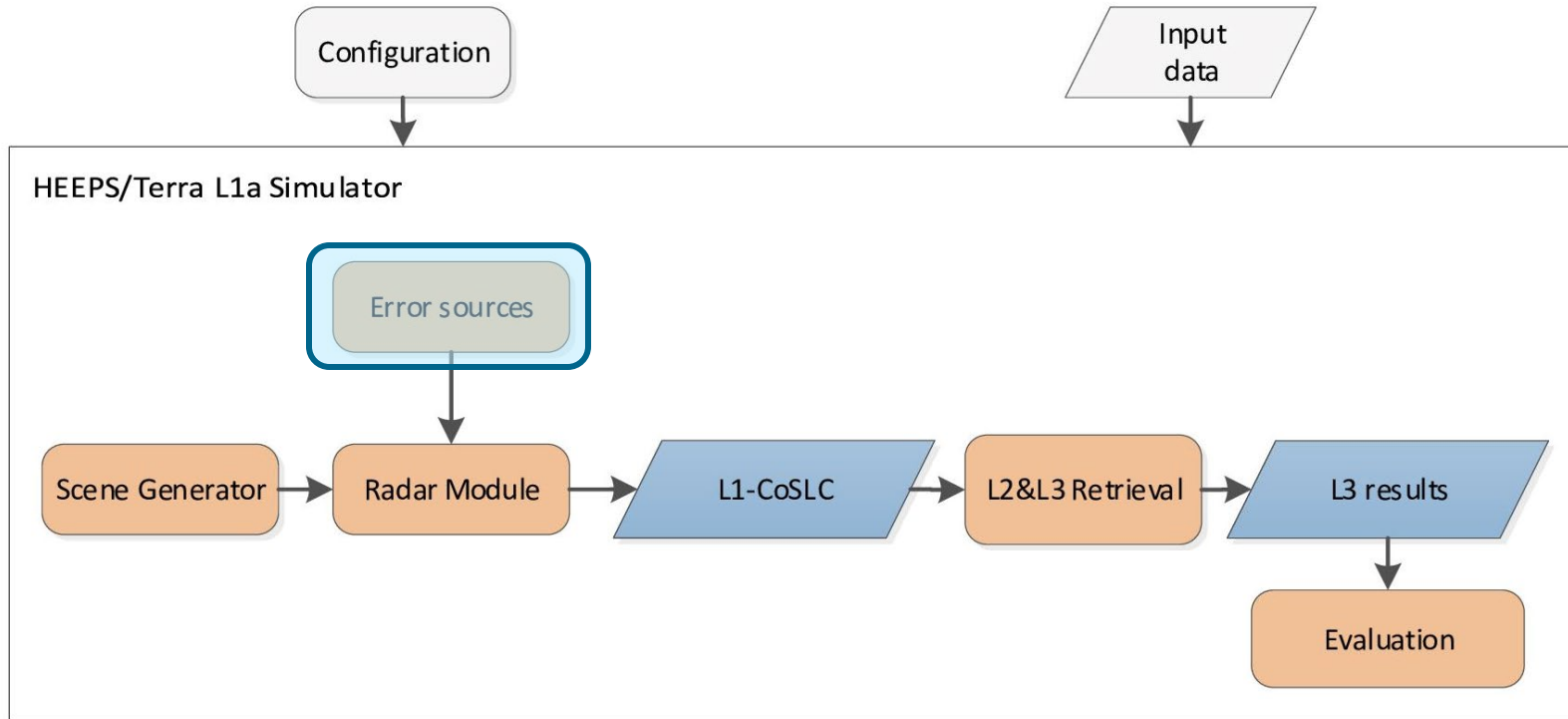
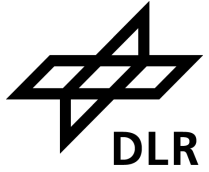
Sentinel-1  
reflectivity image



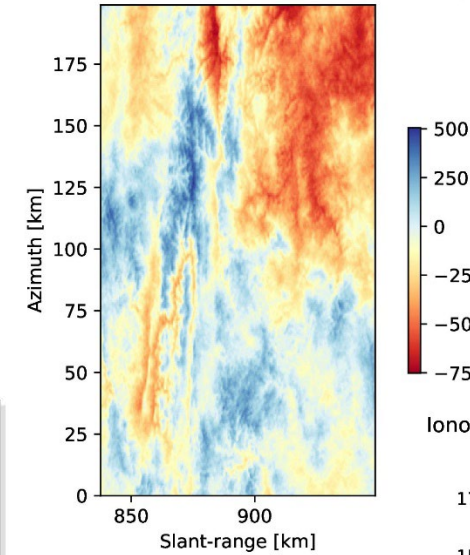
# HEEPS/Terra L1a Simulator – Architecture



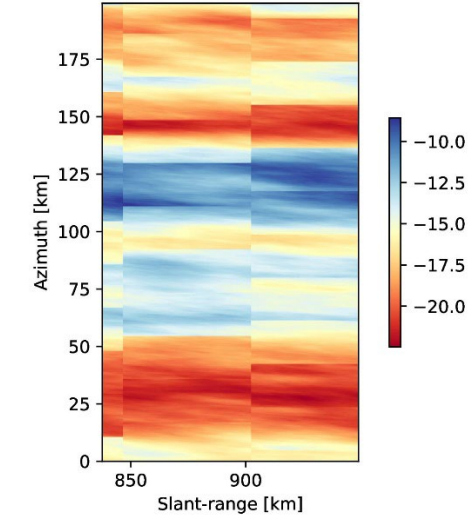
# HEEPS/Terra L1a Simulator – Architecture



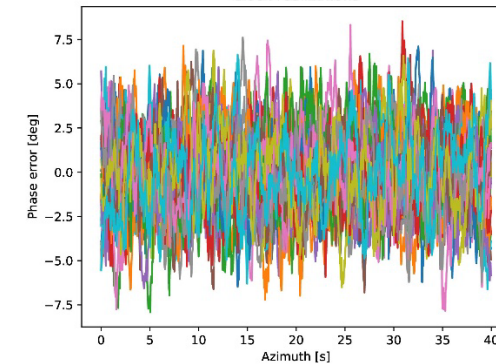
Differential troposphere between two epochs [deg]



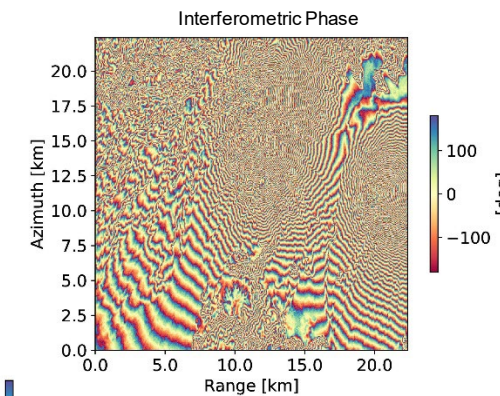
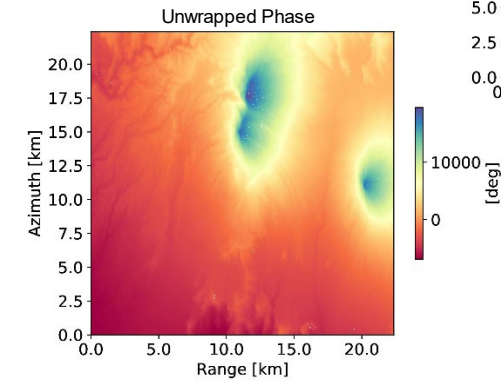
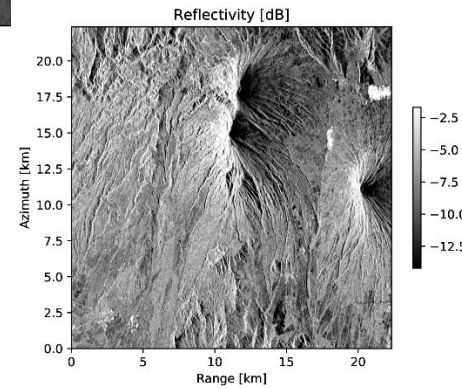
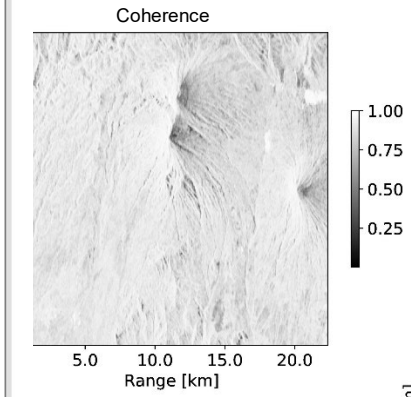
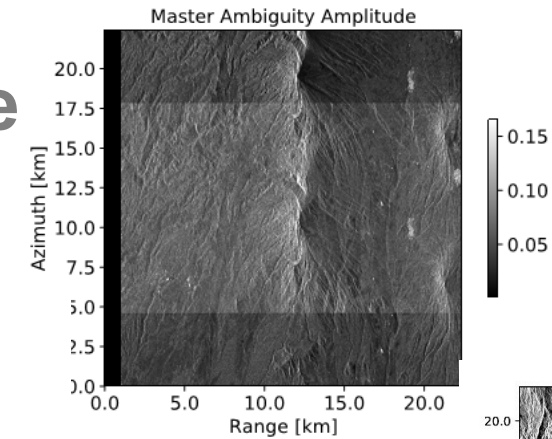
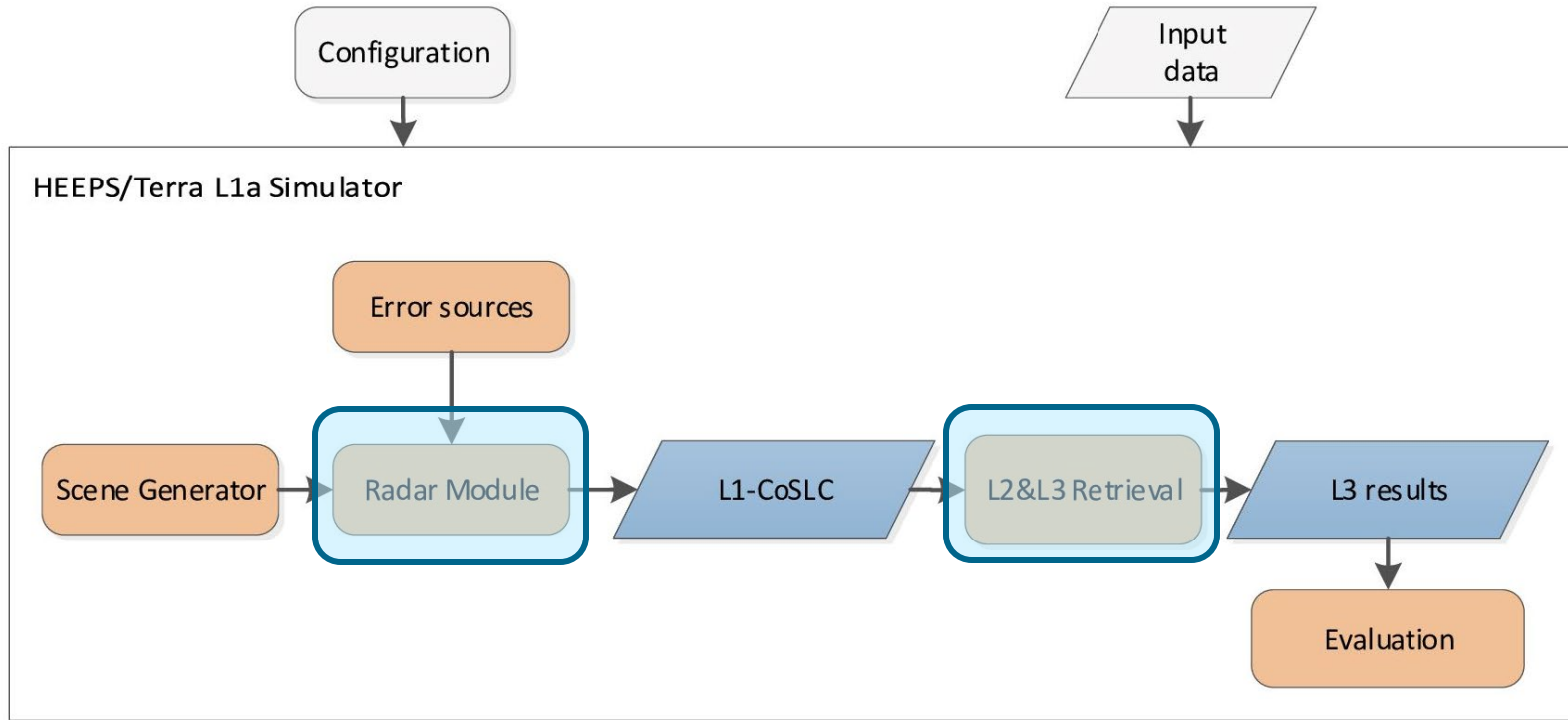
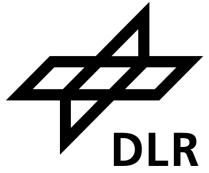
Ionospheric signal for Harmony A [deg]



Clock realizations

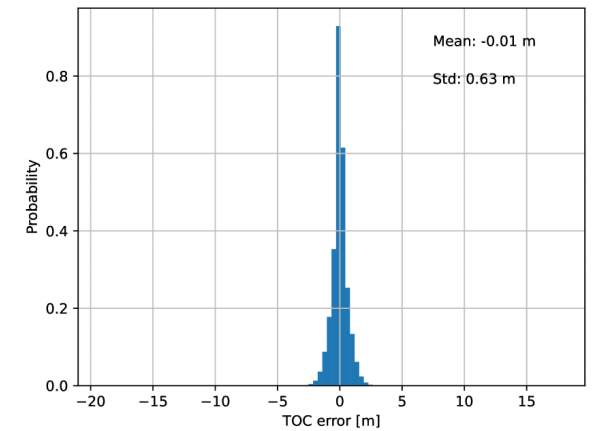
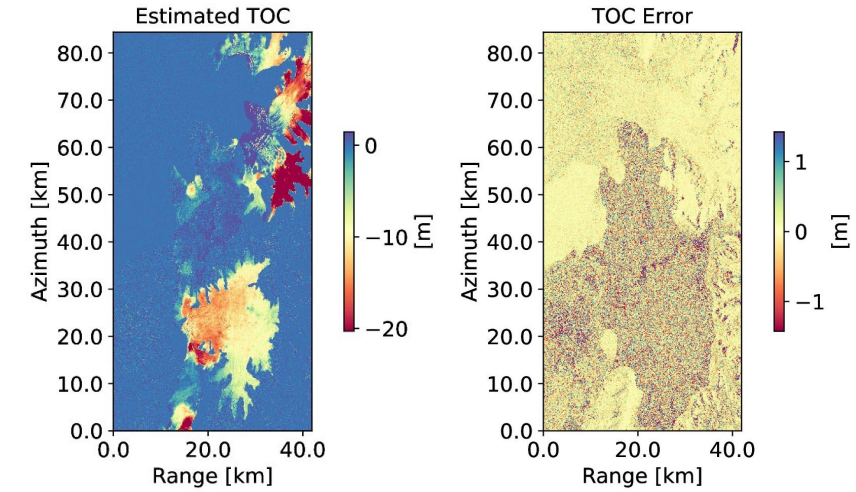
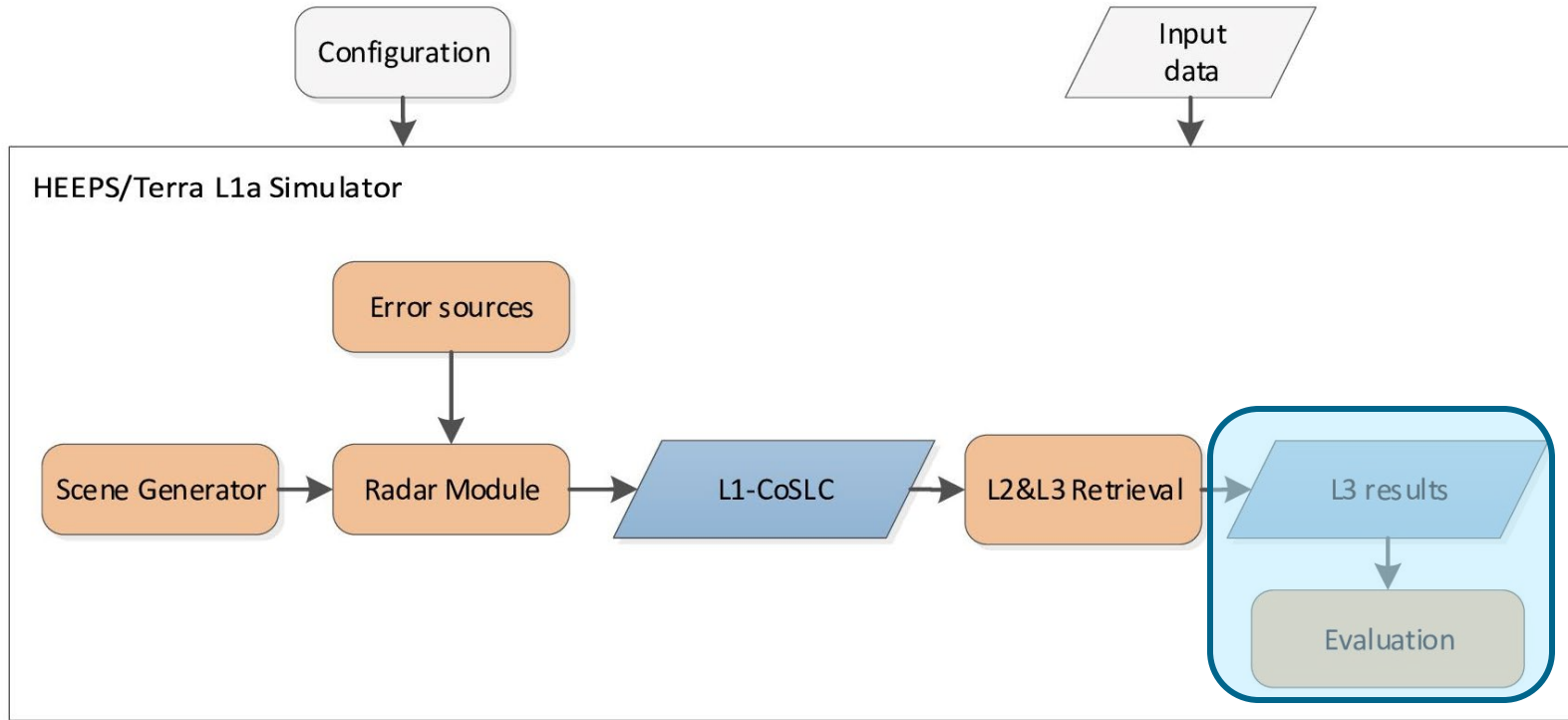
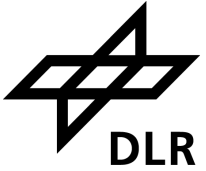


# HEEPS/Terra L1a Simulator – Architecture



- Simulation of large stacks (~900 images for 5 years) for 3-D Velocity Vectors (TDV)

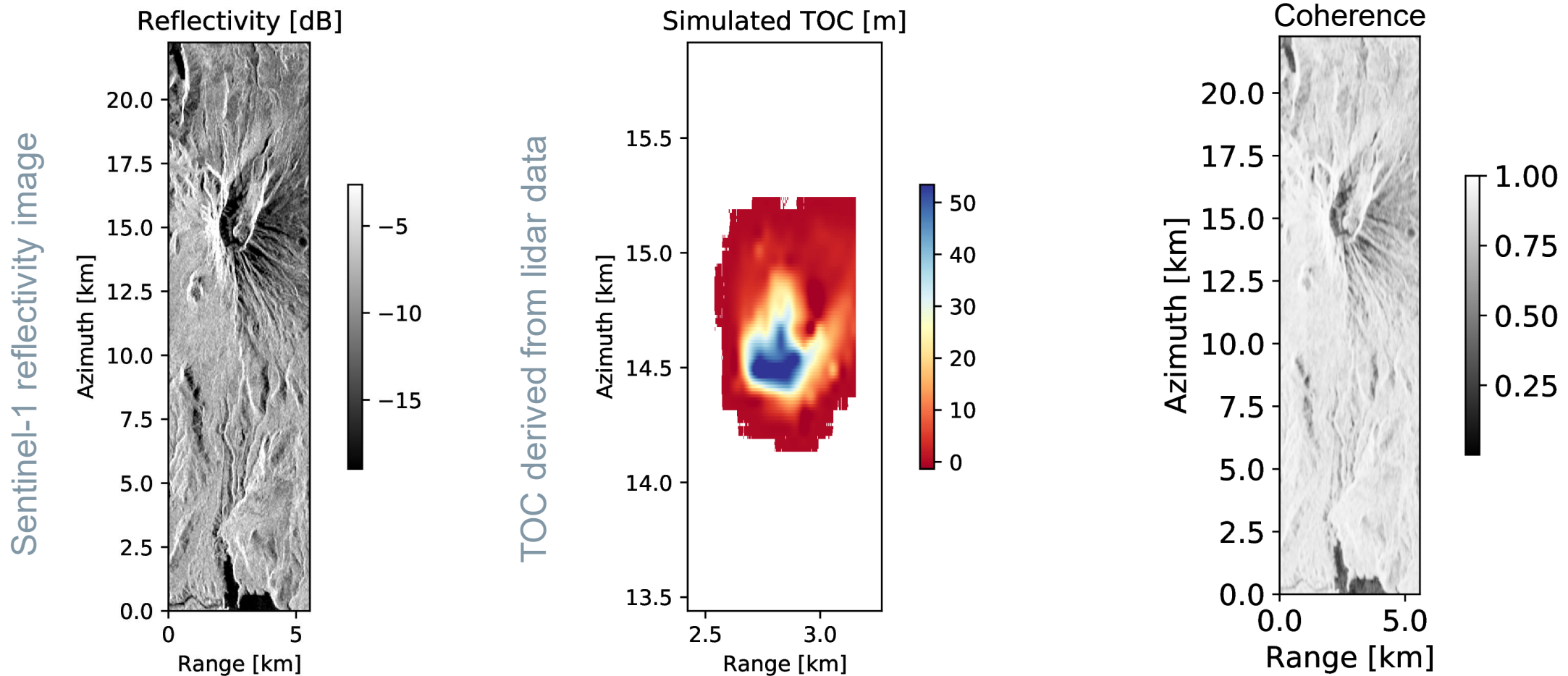
# HEEPS/Terra L1a Simulator – Architecture



# HEEPS/Terra L1a Simulator — L2/L3: TOC Solid Earth



- Mount St. Helens (volcanic dome growth)
- Height of ambiguity: 40 m
- Product resolution: 30 m x 30 m





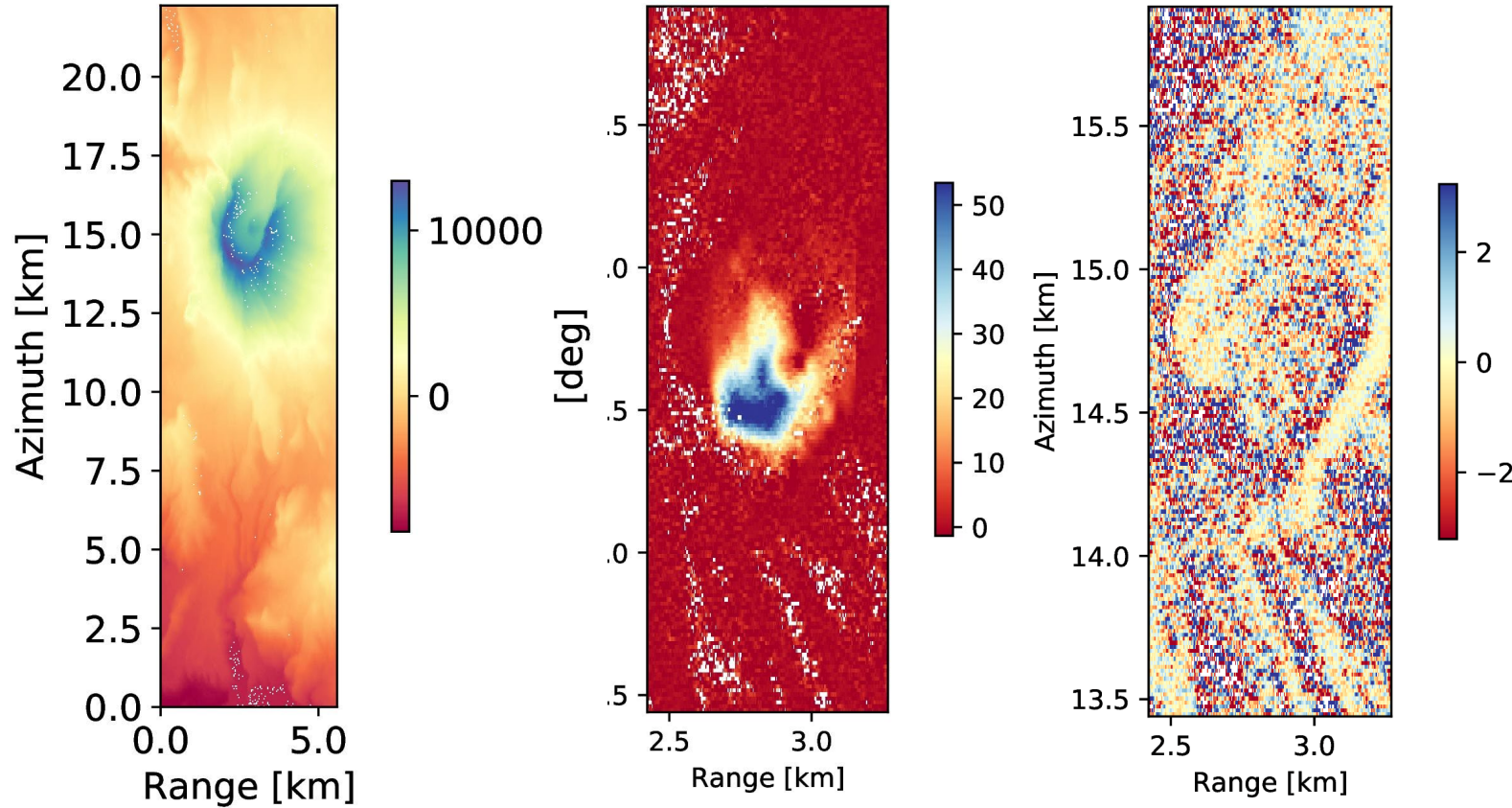
# HEEPS/Terra L1a Simulator — L2/L3: TOC Solid Earth



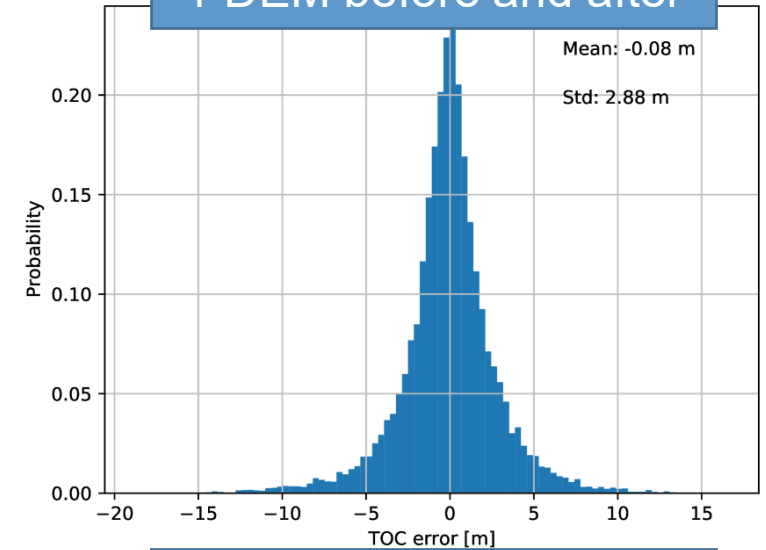
Unwrapped Phase

Estimated TOC [m]

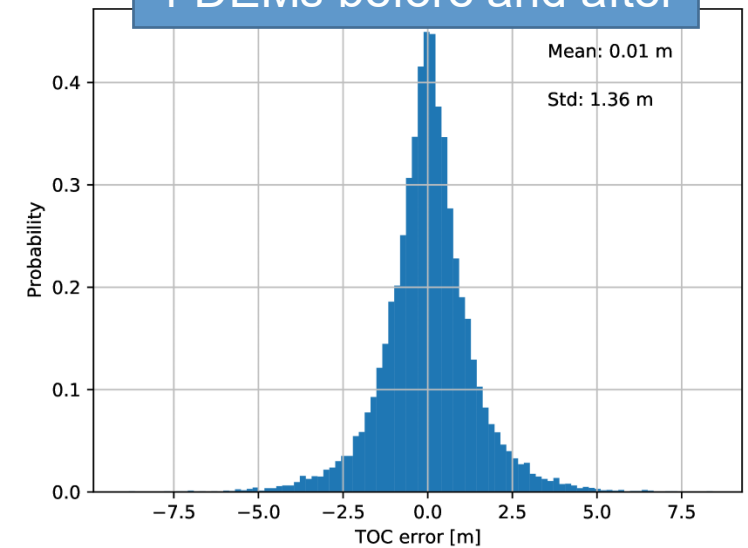
TOC error [m]



1 DEM before and after



4 DEMs before and after



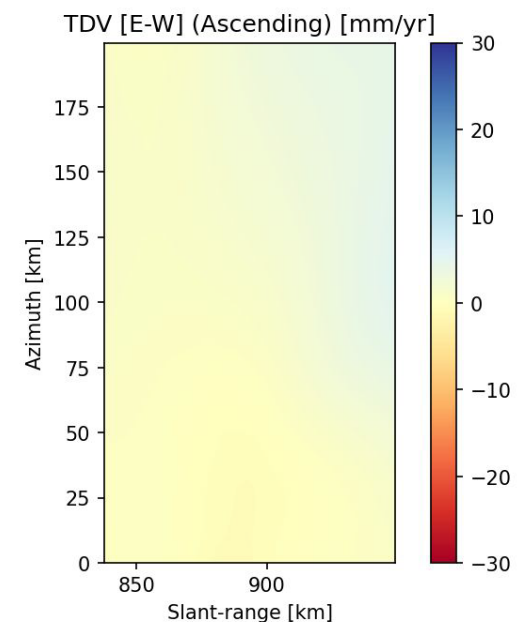
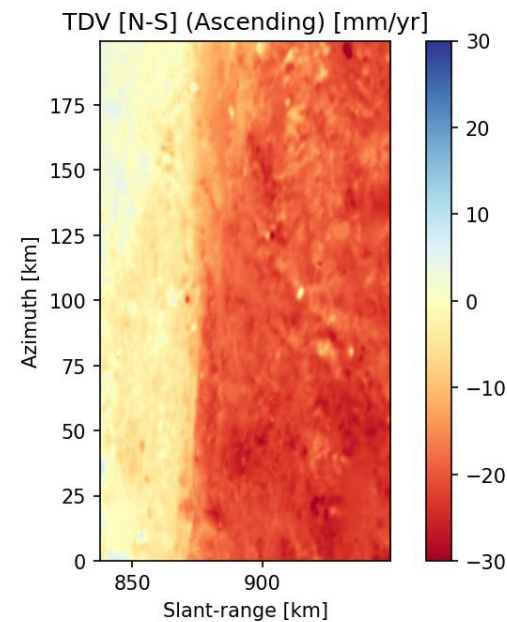
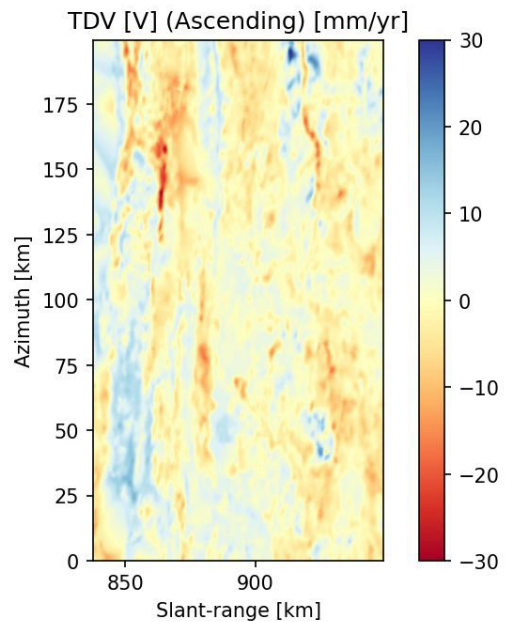
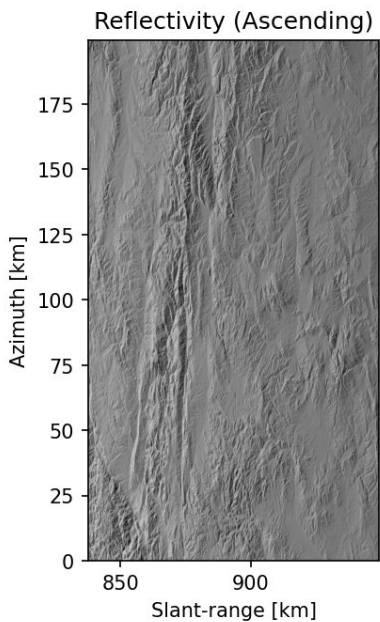
Performance within requirement for large baselines (height of ambiguity  $\leq 30$  m), or by averaging consecutive DEMs:

1 m at 30 m x 30 m resolution

# HEEPS/Terra L1a Simulator — L3: TDV Solid Earth



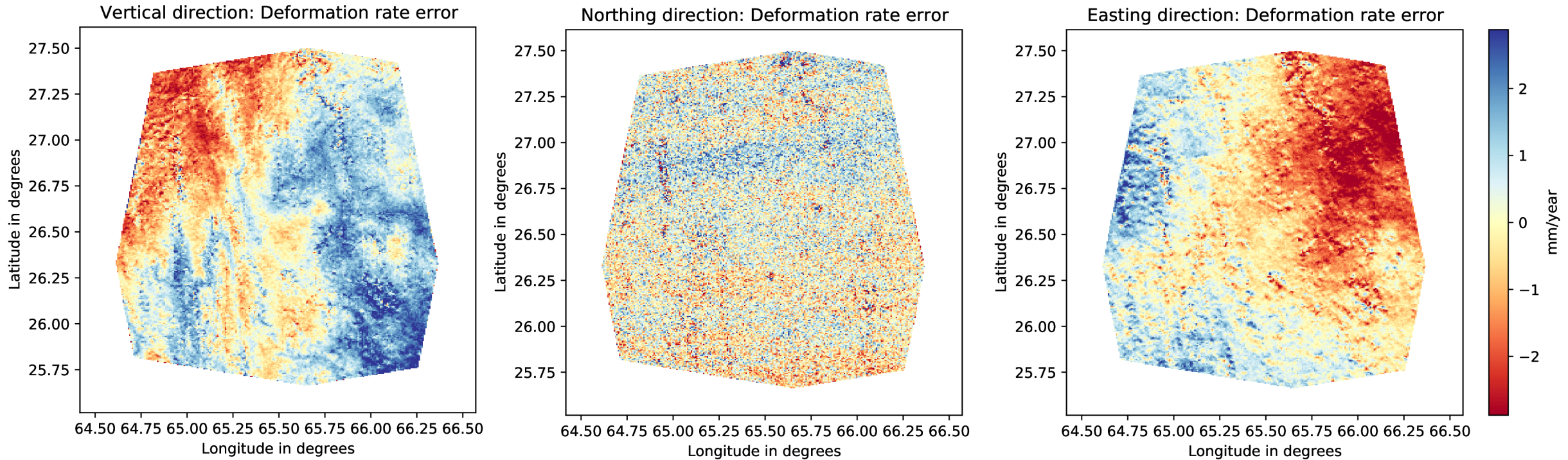
Test Case	Description	Comment	Test Data Set
Scenario #1	5 years Stereo	Ideal (for reference)	Rotated North Anatolian fault deformation derived from Sentinel-1 time series
Scenario #2	Asc&Desc with Harmony	Best N-S performance	
Scenario #3	Only one configuration with Harmony	Worse N-S performance than scenario #2	
Scenario #4	Asc&Desc with Harmony + 5 extra years Sentinel-1	Improved performance for E-W and vertical components	



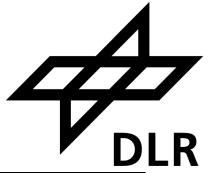
# Rotated North Anatolian Fault — Scenario #2



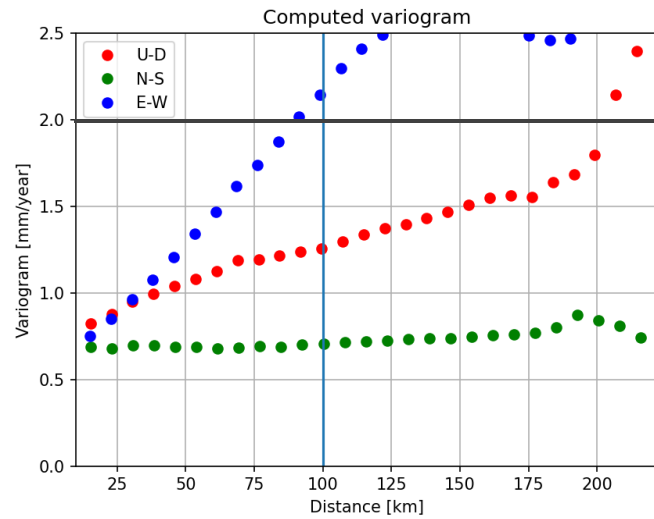
## L3 product: 3-D Velocity Vectors



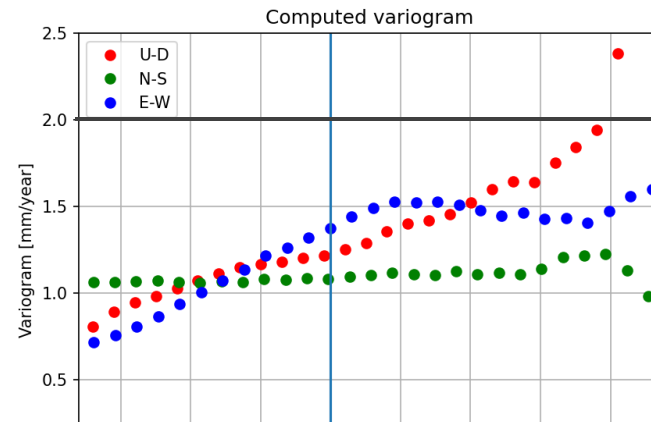
# Rotated North Anatolian Fault — Simulated Scenarios



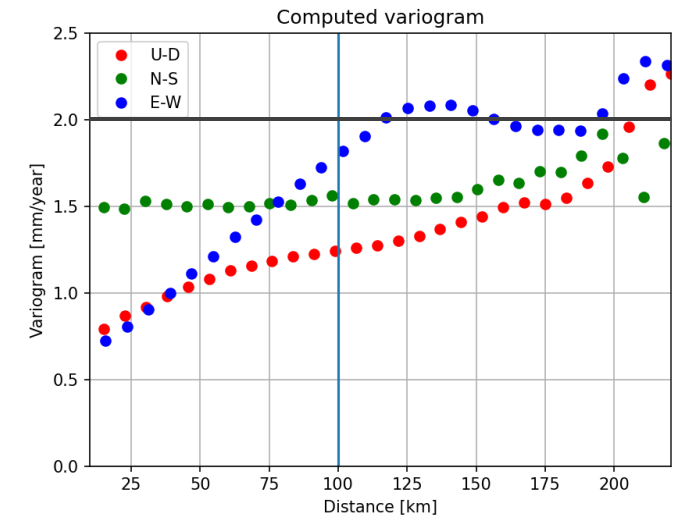
## Scenario #1



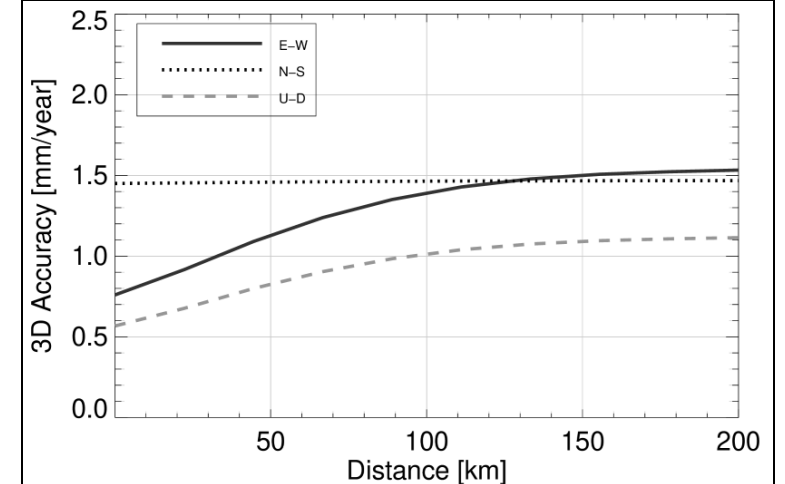
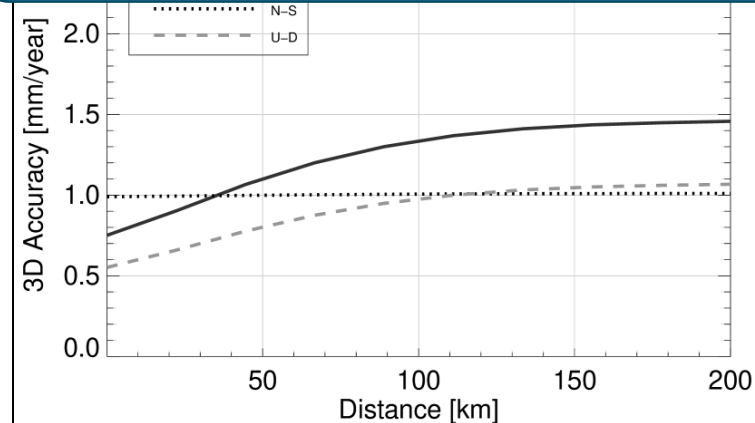
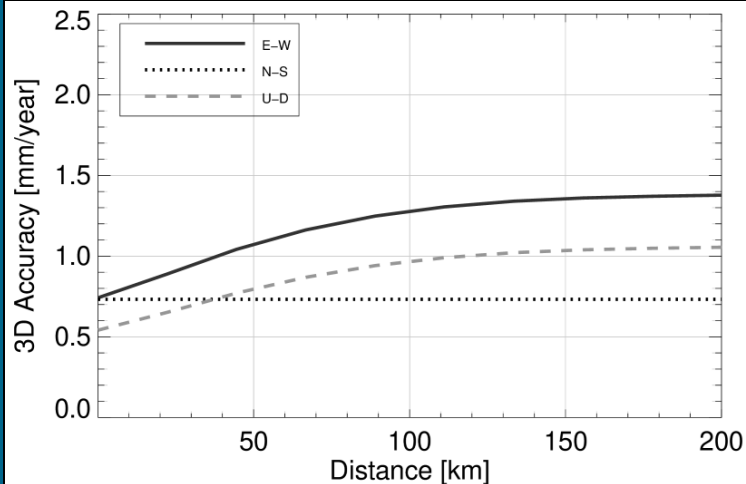
## Scenario #2



## Scenario #3



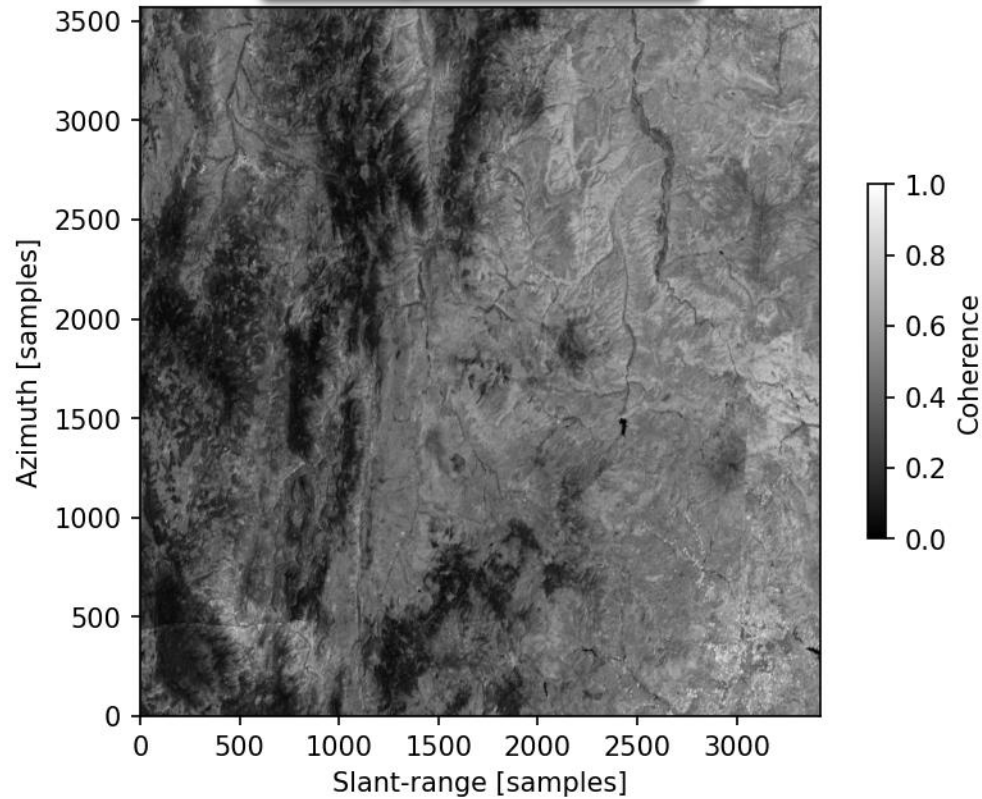
Good agreement between simulation and performance model



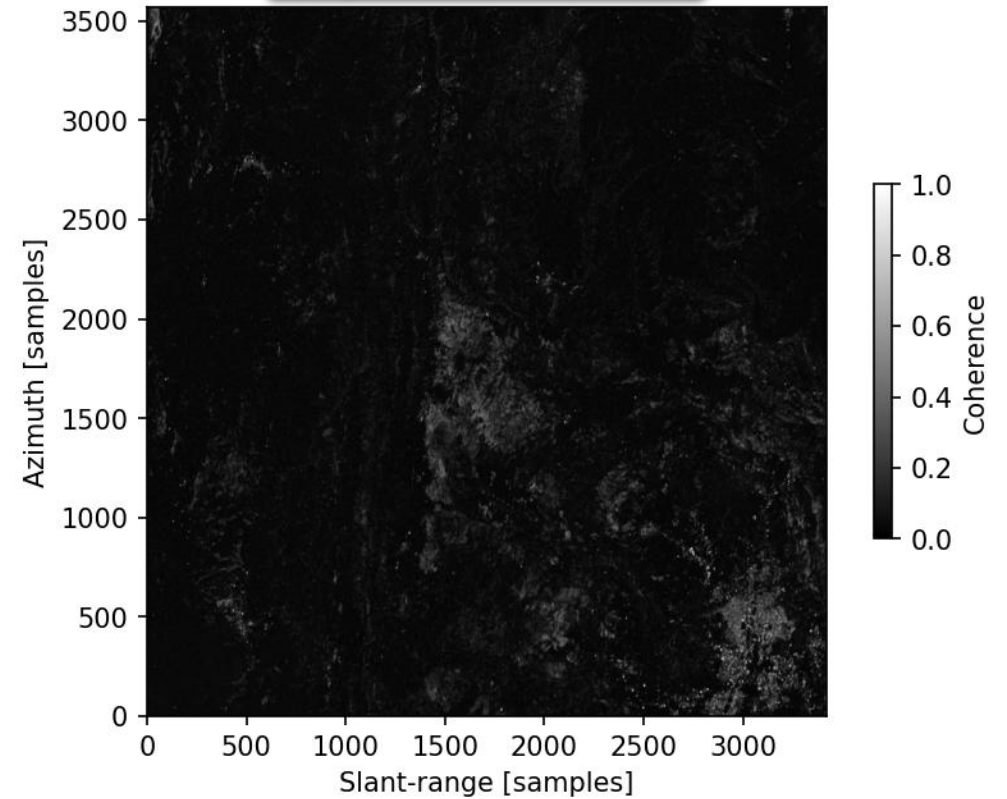
# Rotated North Anatolian Fault — S1 Real Covariance



6-day coherence



5-year coherence



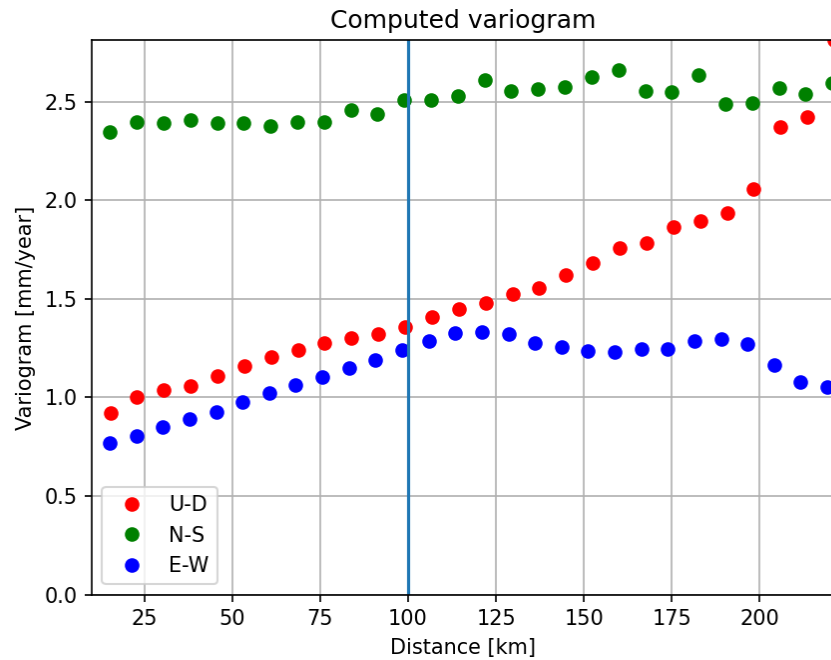
→ Time

# Rotated North Anatolian Fault — S1 Real Covariance



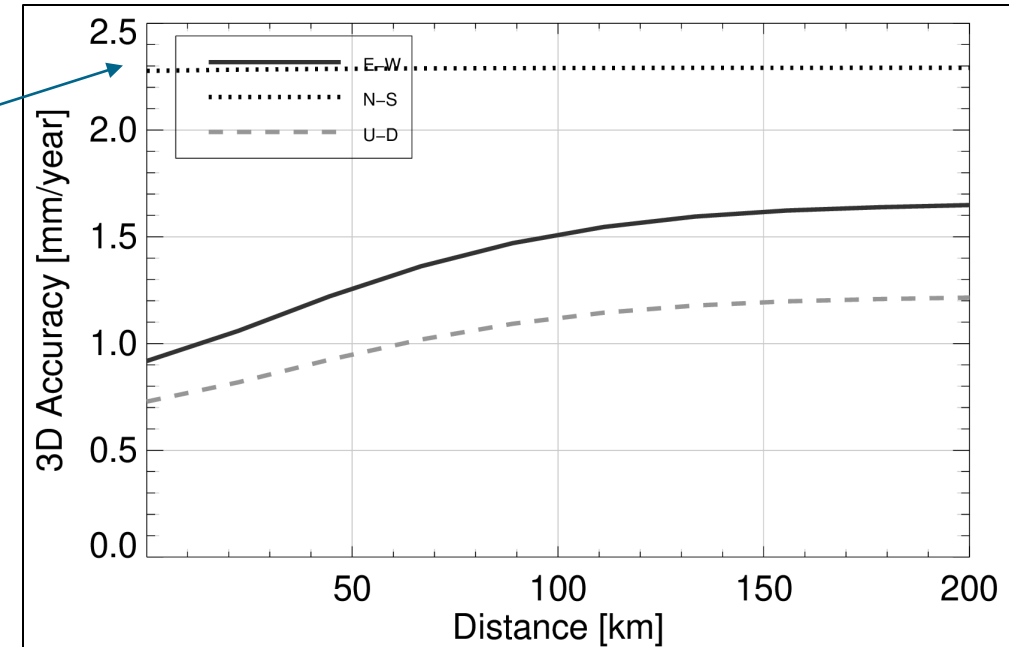
Time

End-to-End Simulation

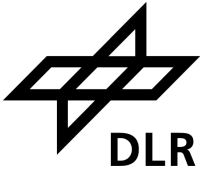


Larger "noise" scaling for the N-S

Analytical Performance Model

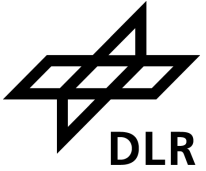


# Summary and Way Forward



- Good agreement between analytical performance models and end-to-end simulations
- Goal requirements are met. On the other hand:
  - Assumptions
  - Challenging in some scenarios
- HEEPS/Terra Simulator(s) to be further extended during the next phases of the Harmony mission in order to improve the performance prediction and consolidate the L1/L2/L3 processing and calibration algorithms

# Additional Information



- More details on HEEPS/Terra can be found at the User Consultation Meeting portal (Report for Mission Selection and UCM slides)

<https://atpi.eventsair.com/ucm-2022/ucm-doc>

